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EUROGRAPHICS 2023

Learning to Learn and Sample BRDFs

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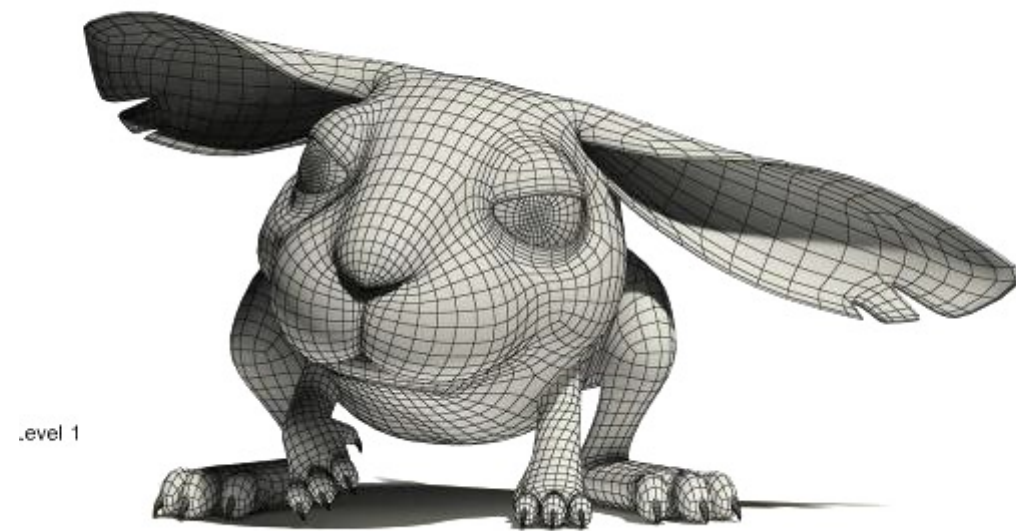
Motivation

Assets

Content



=



Shape

+



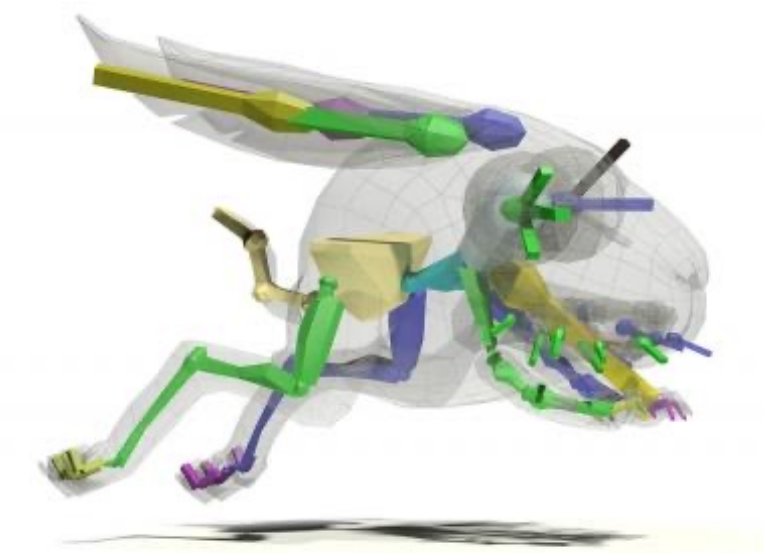
Material

+



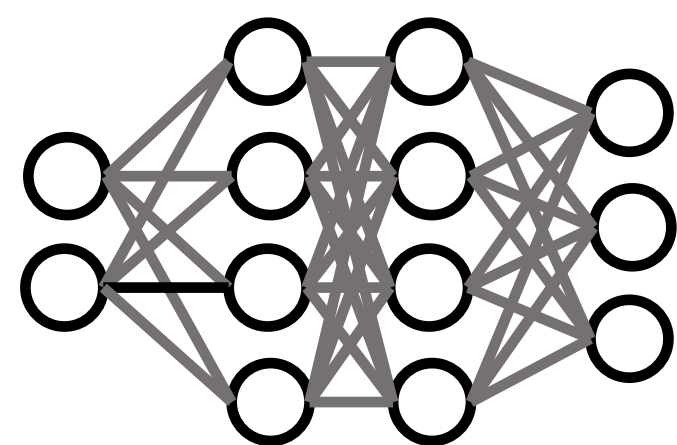
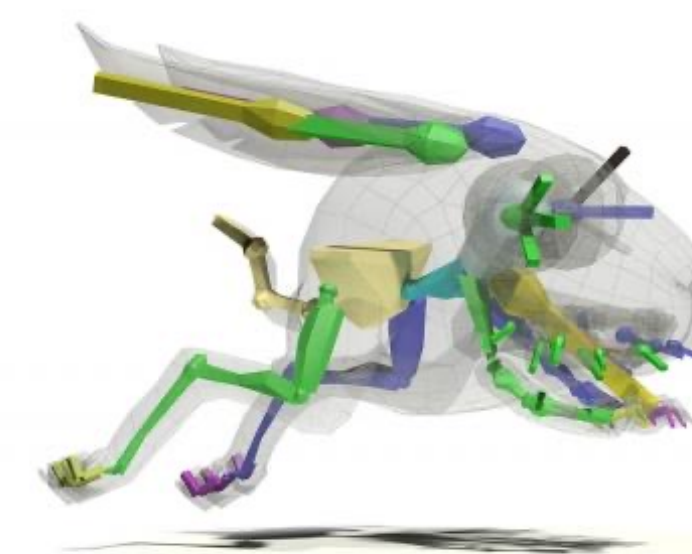
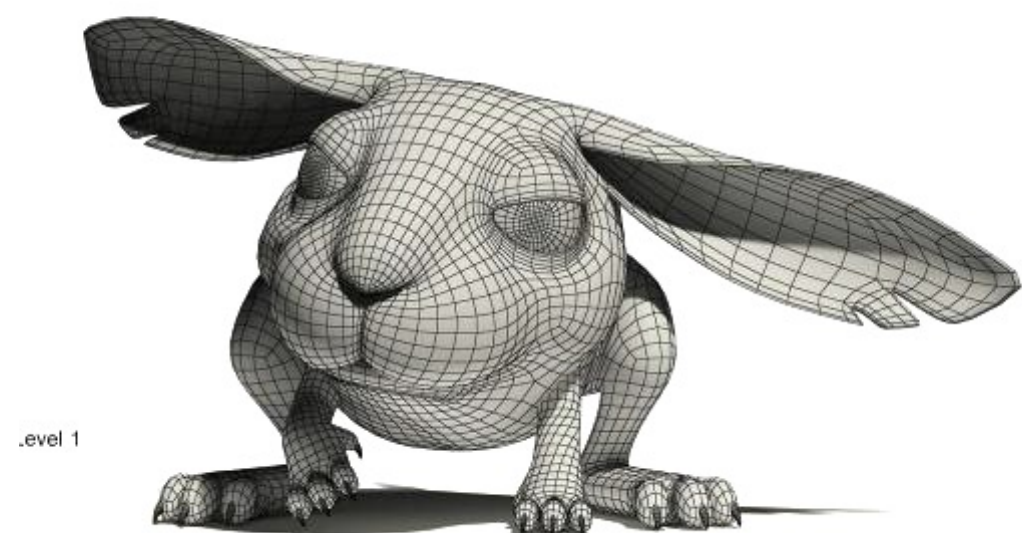
Illumination

+

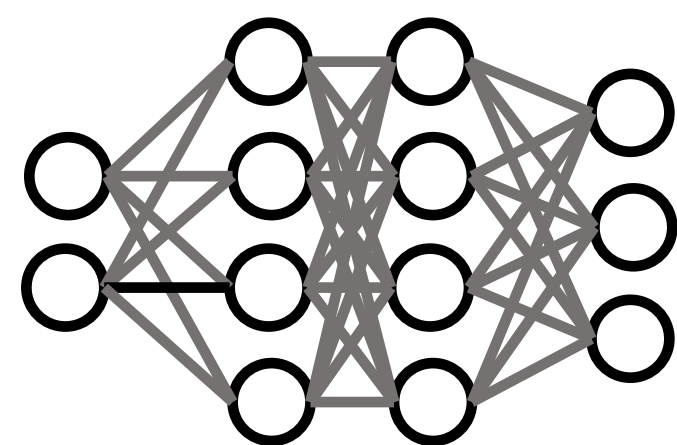


Animation

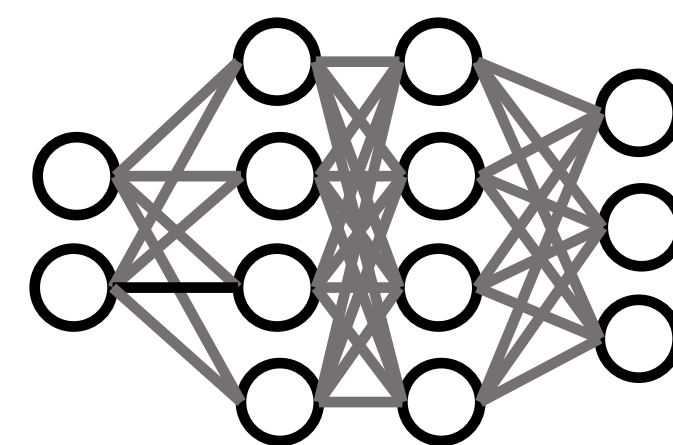
Neural assets



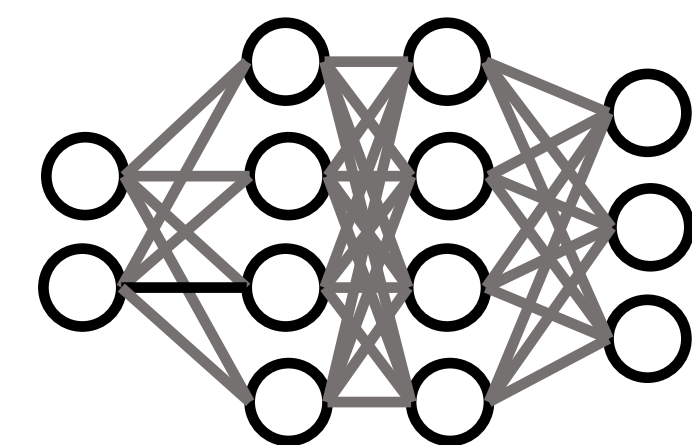
Shape



Material



Illumination

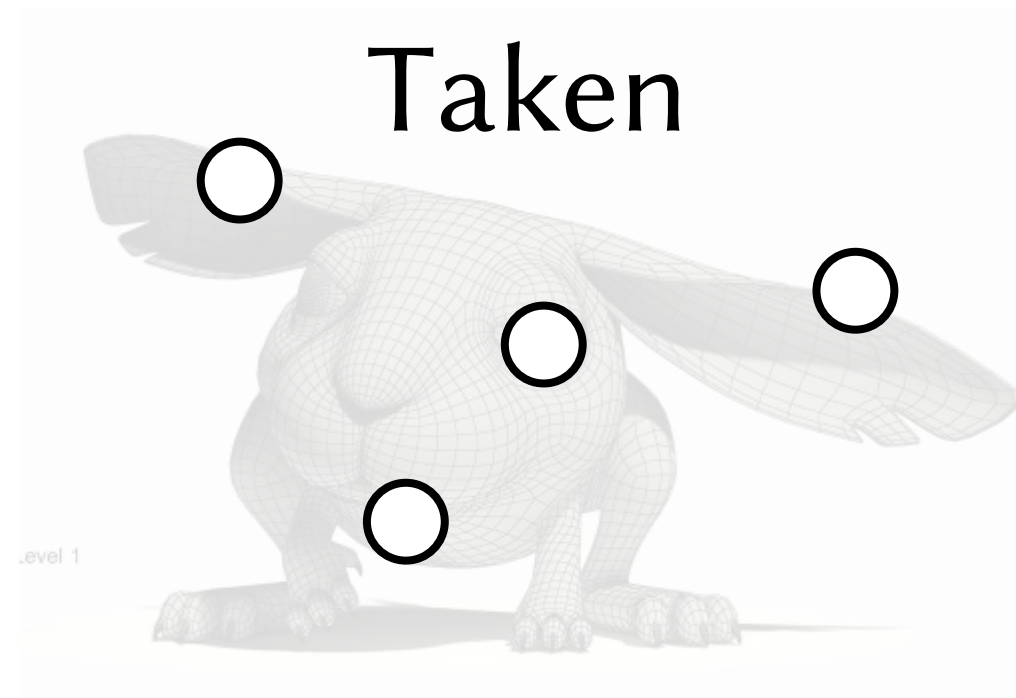


Animation

Sampling



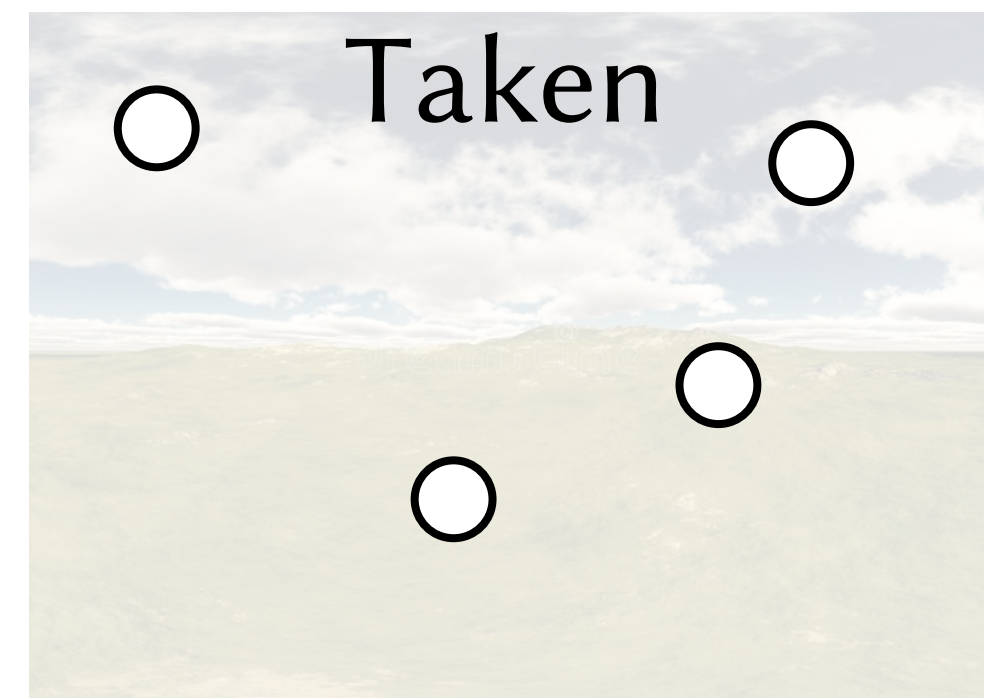
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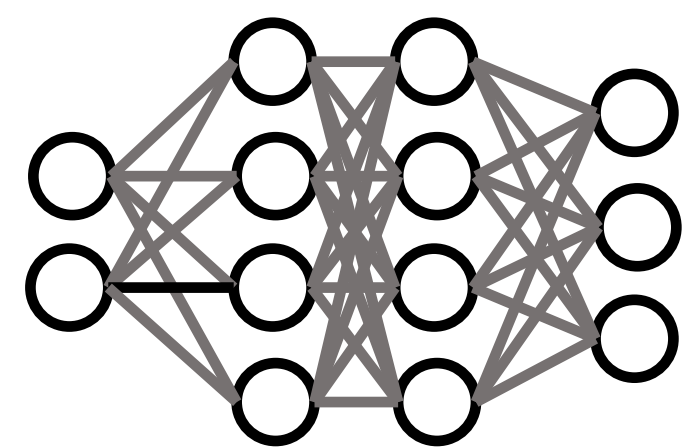
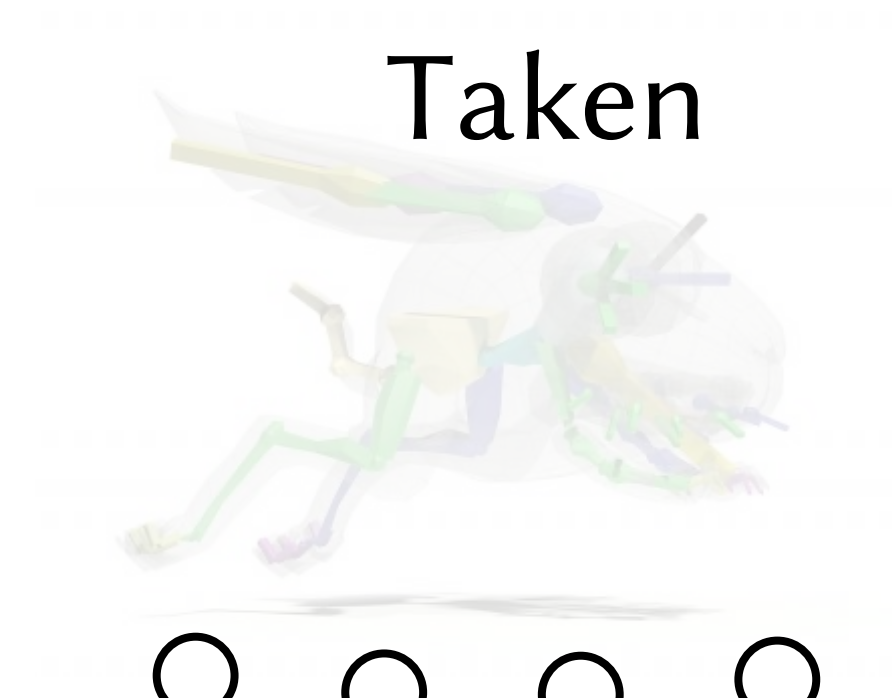
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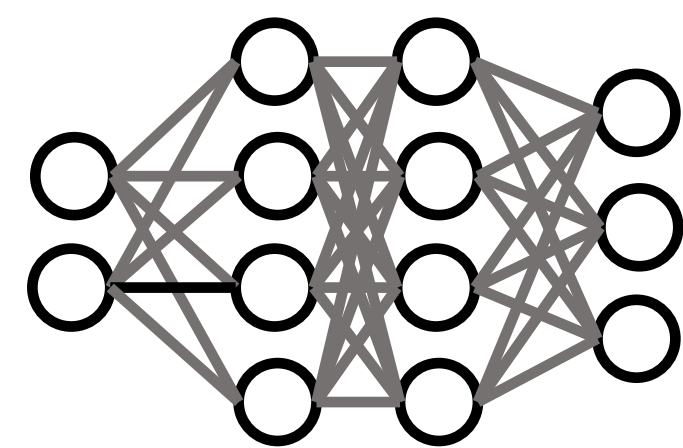
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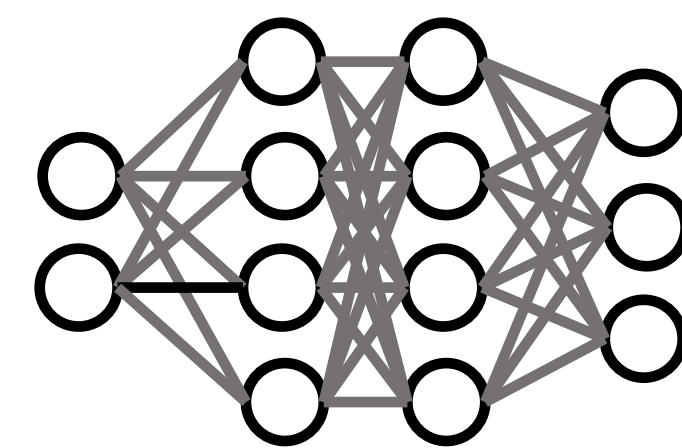
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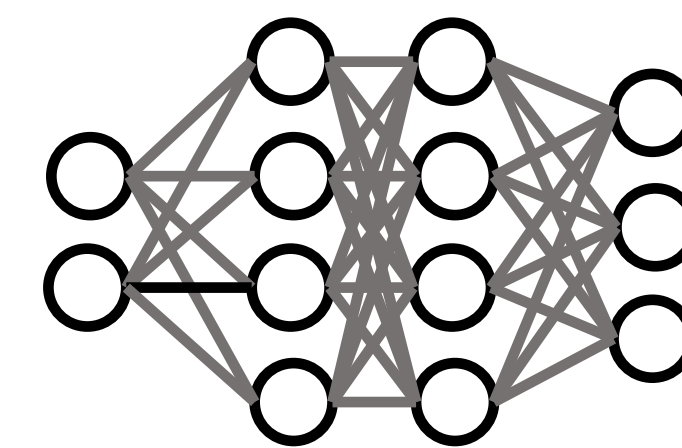
Optimized



Optimized

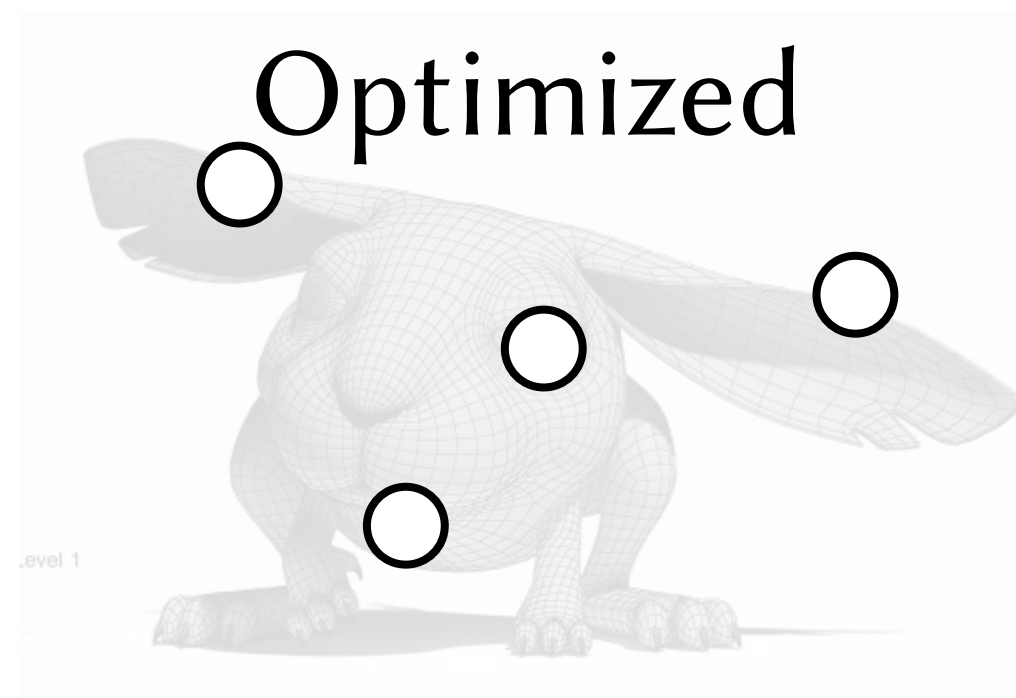


Optimized

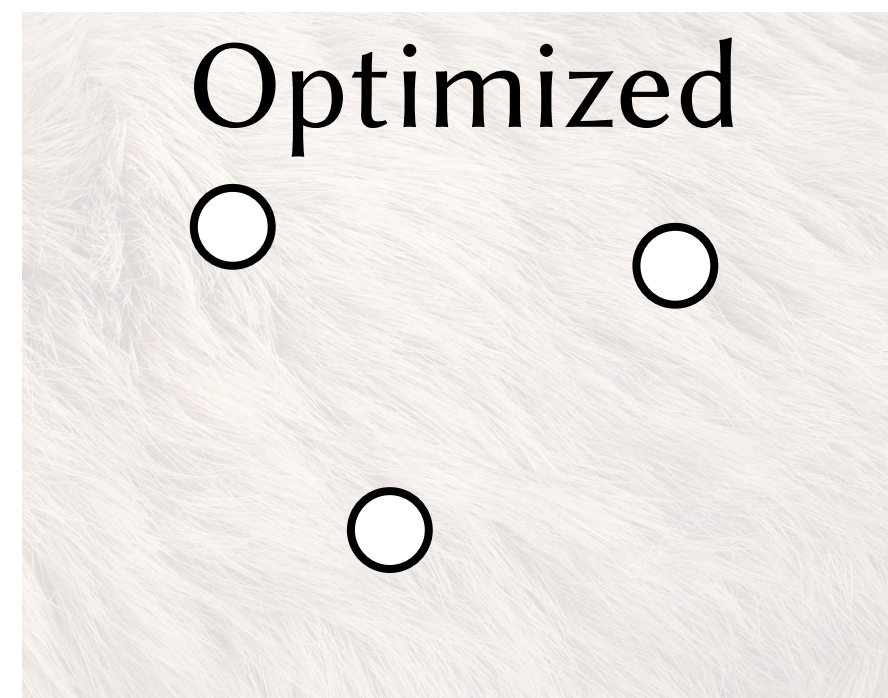


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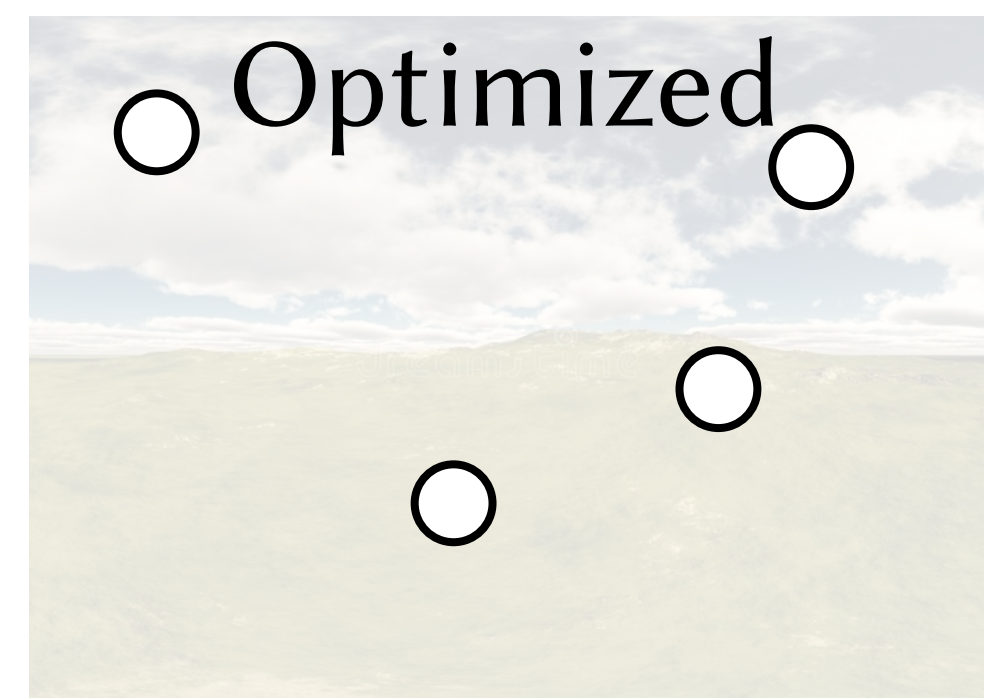
Also optimize sampling



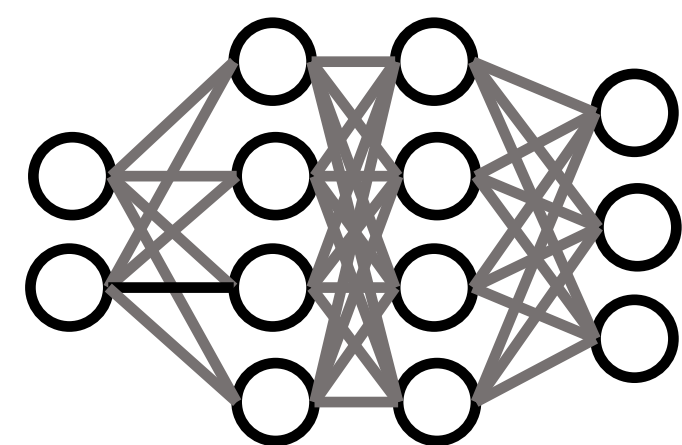
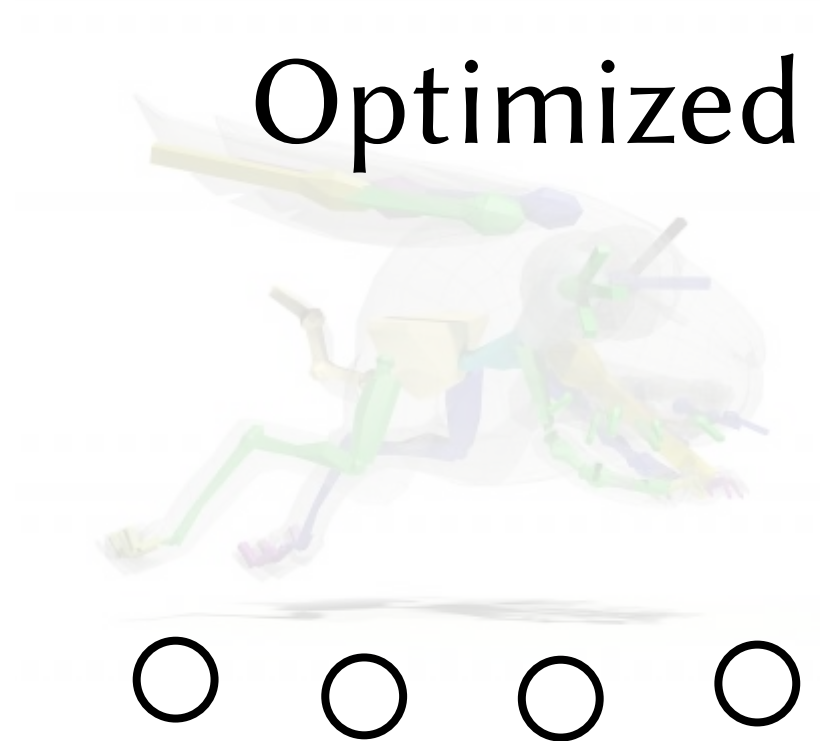
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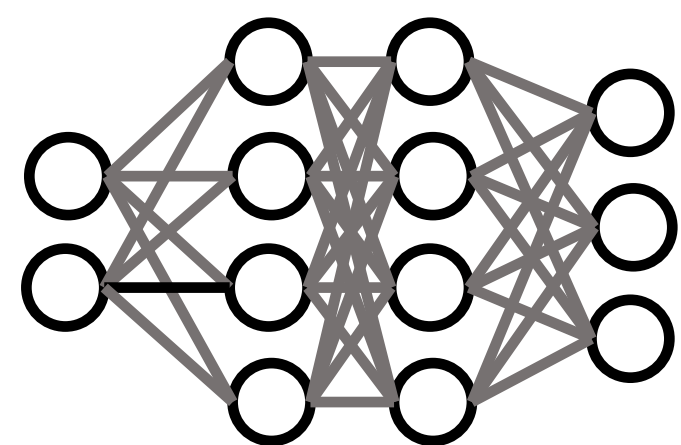
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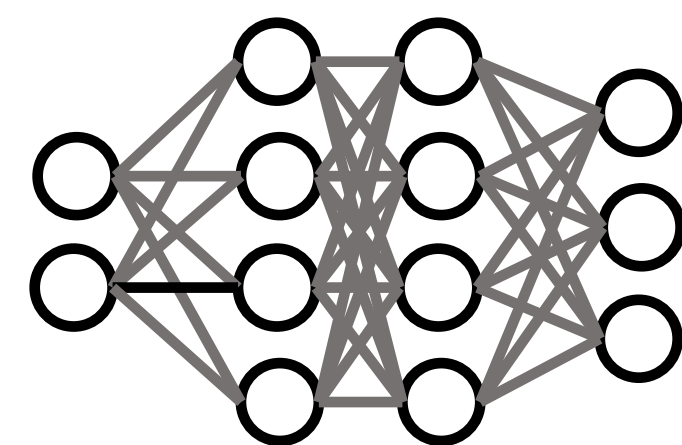
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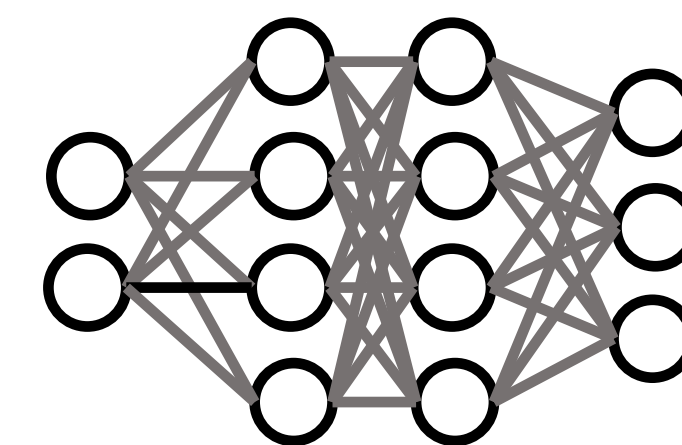
Optimized



Optimized



Optimized

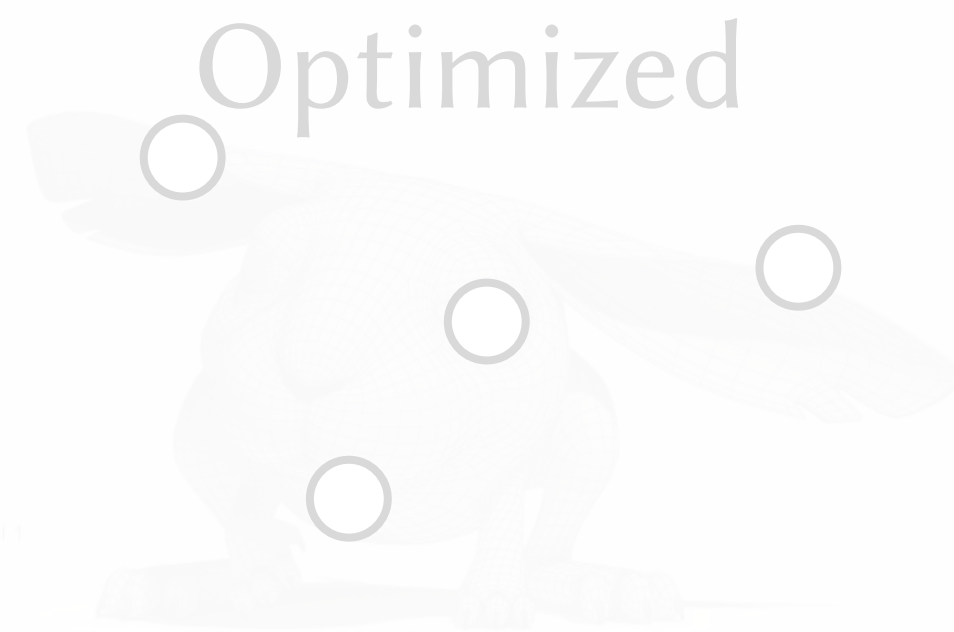


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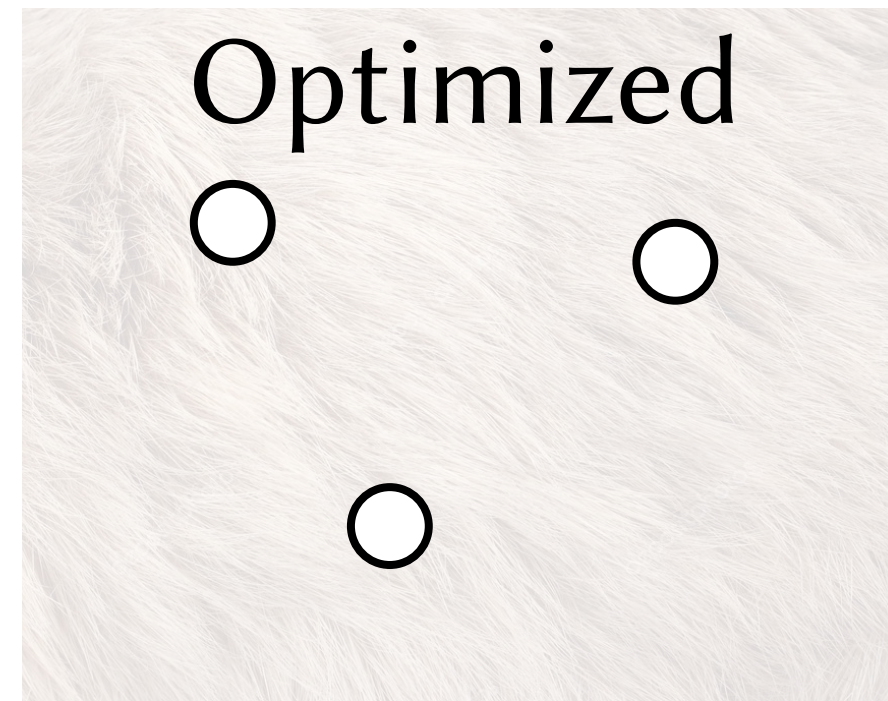
We look at the BRDF case



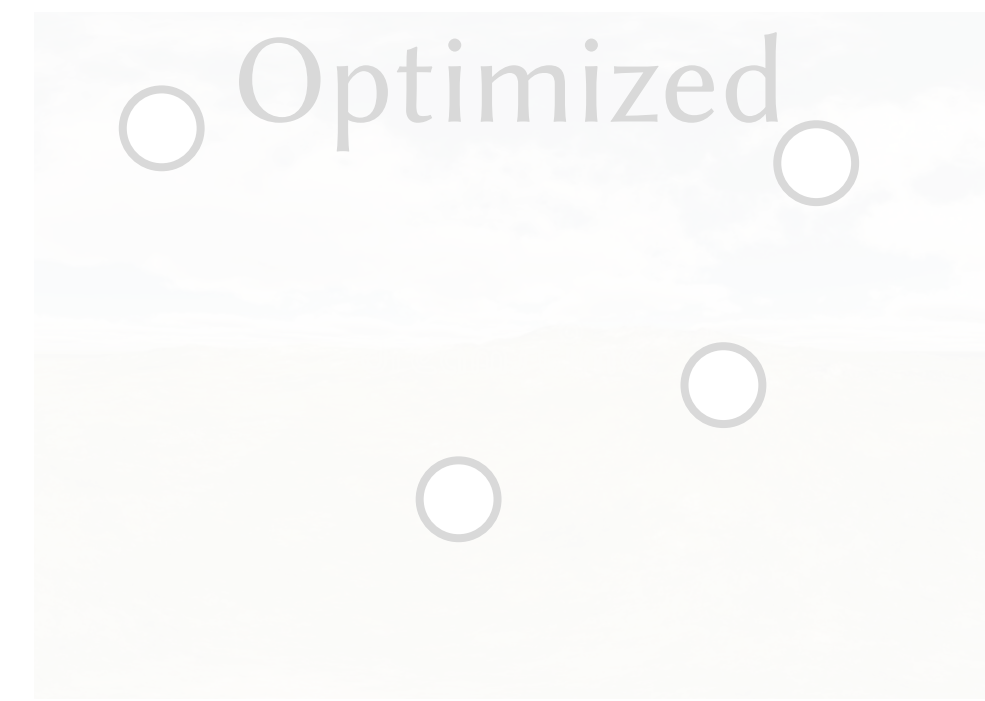
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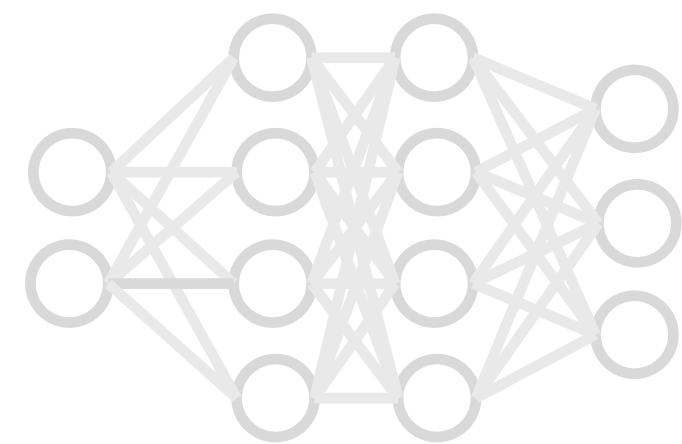
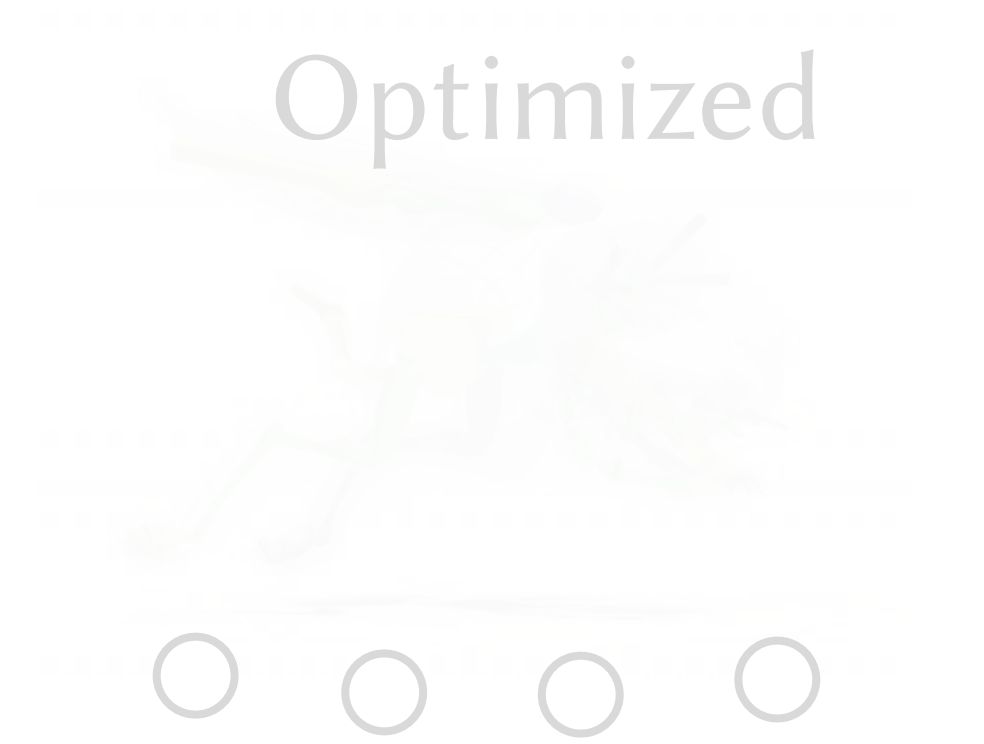
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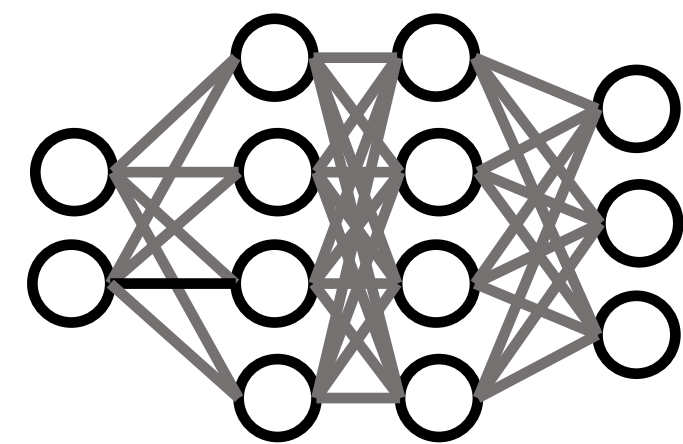
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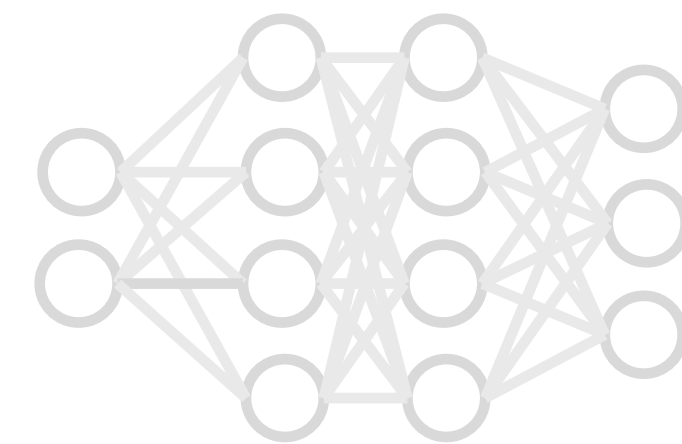
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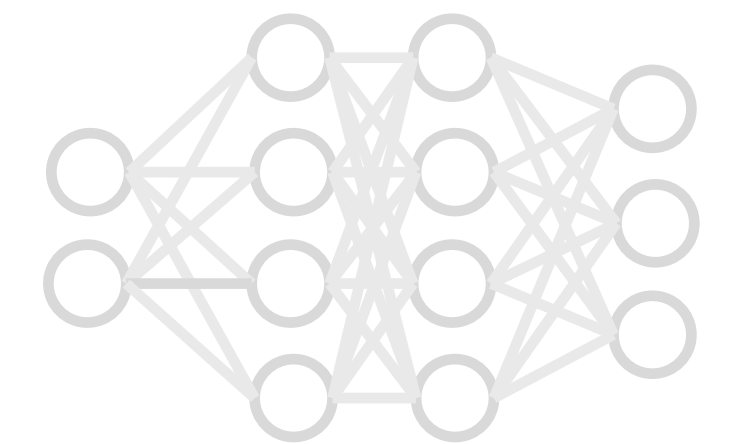
Optimized



Optimized

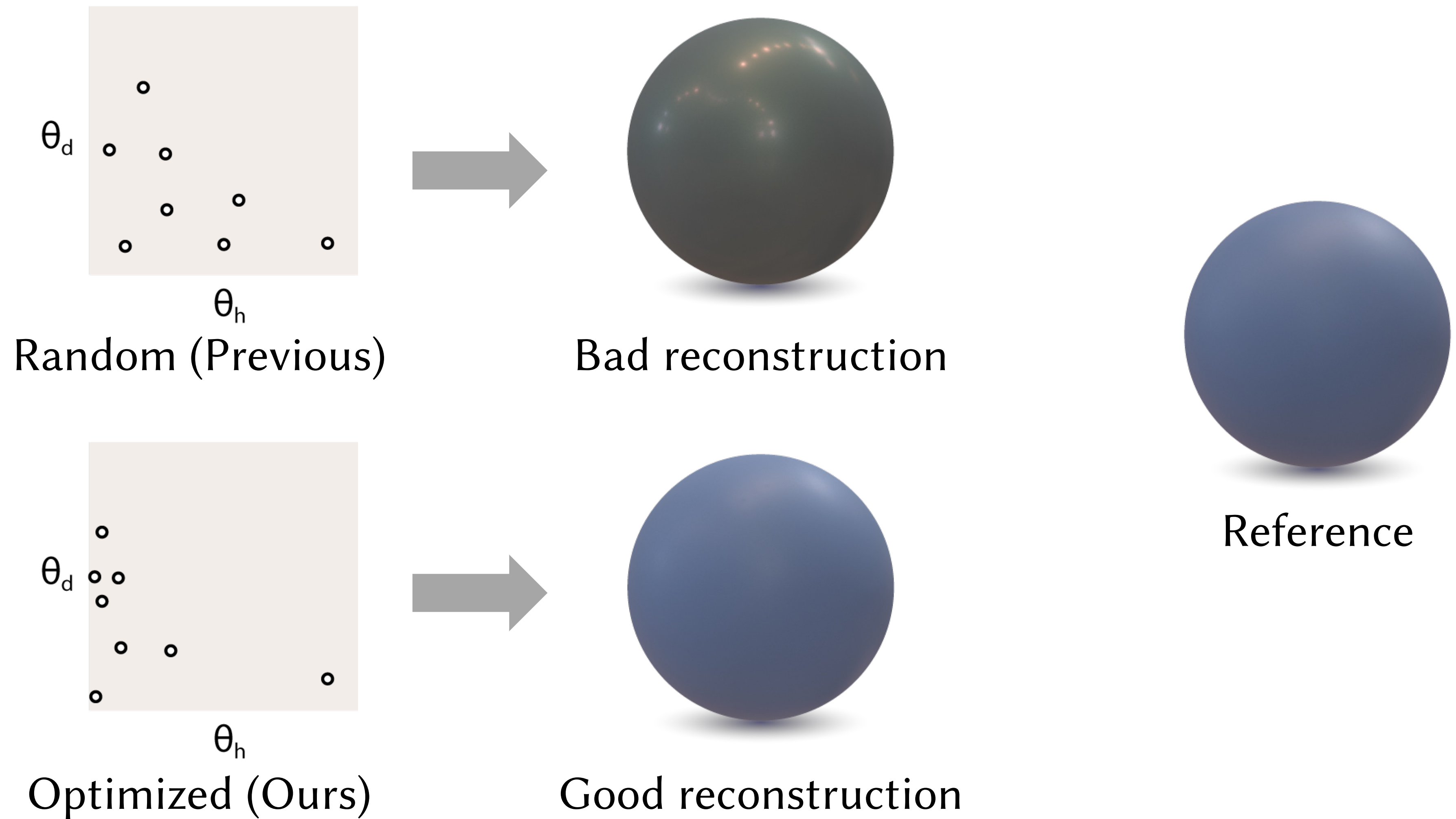


Optimized



Optimized

Not all samples are equally useful



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Related work

Backbone BRDF models

1) Analytical models

- Phong [PB75]
- Cook-Torrance [CT82]

$$f_r(\omega_i, \omega_o) = k_d \frac{1}{\pi} + k_s \frac{q + 2}{2\pi} \langle \omega_o, r \rangle^q$$

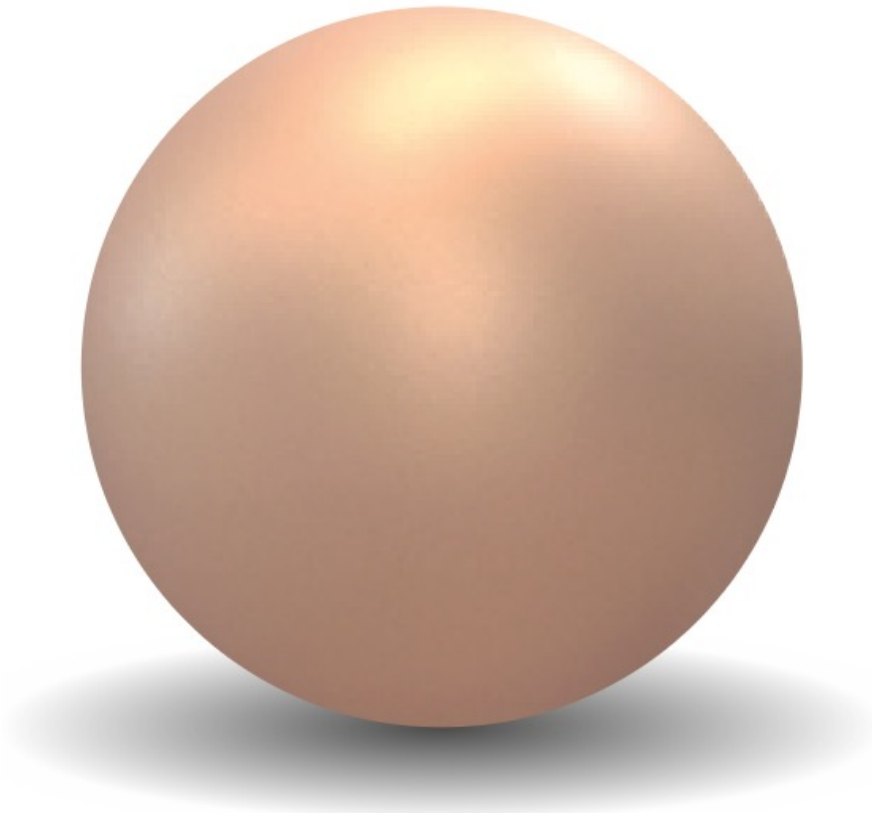
$$f_r(\omega_i, \omega_o) = k_d \frac{1}{\pi} + k_s \frac{D(\alpha)GF(F_0)}{\pi \cos(\theta_i) \cos(\theta_o)}$$

Optimize parameters

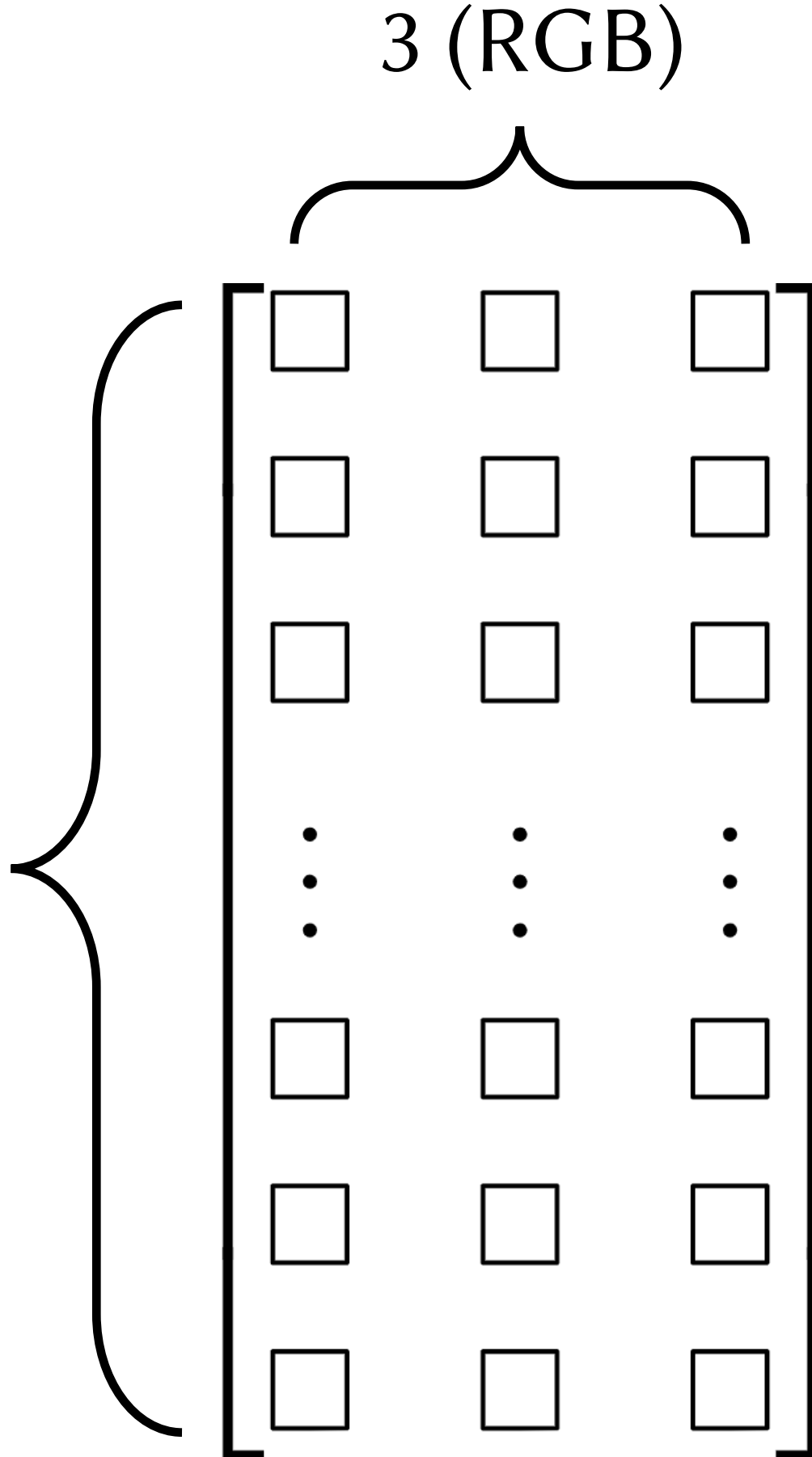
Backbone BRDF models

2) Linear PCA model [Mat03] [NJR15]

- MERL Dataset

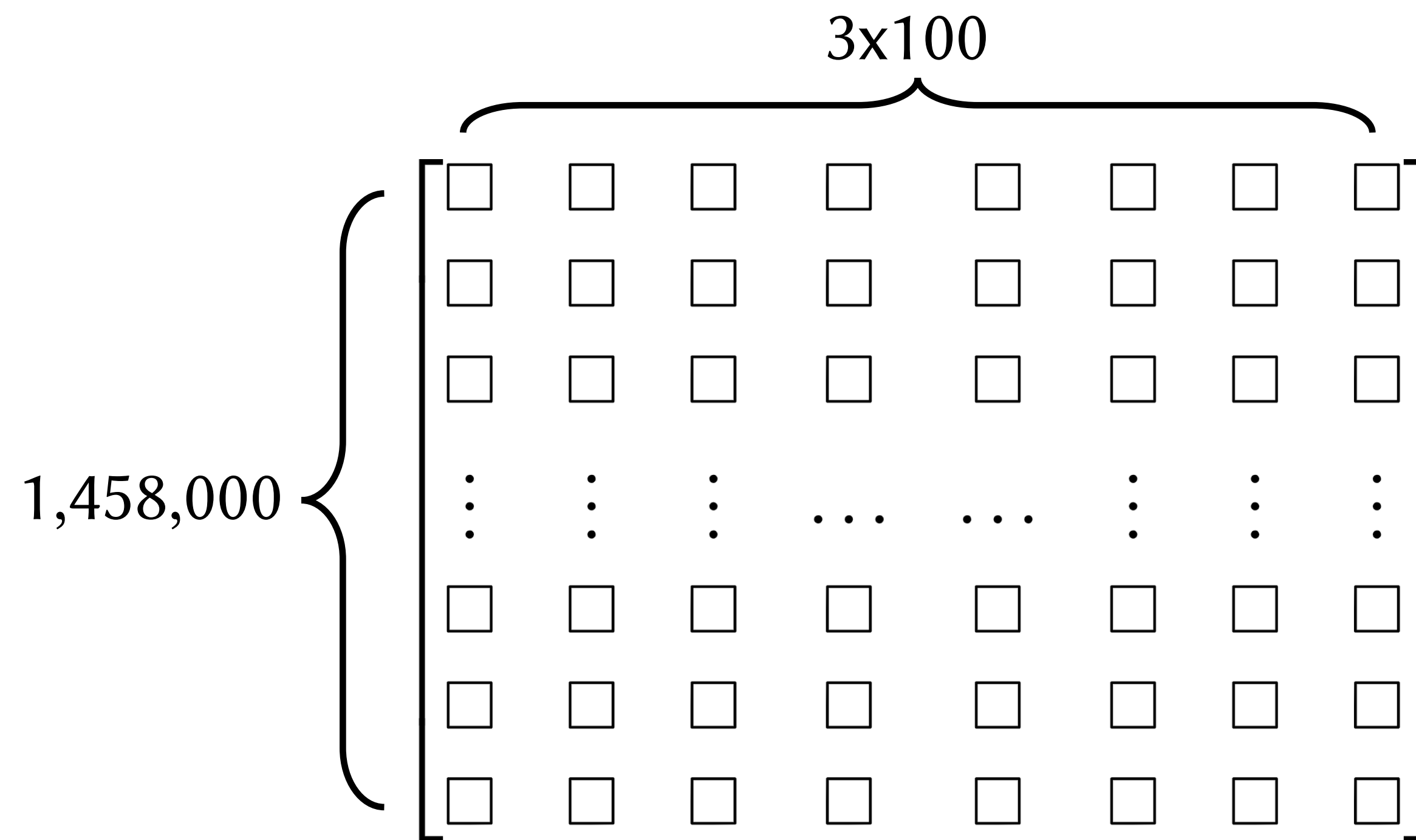


Measured in the resolution of $90 (\theta_h) \times 90 (\theta_d) \times 180 (\phi_d) = 1,458,000$

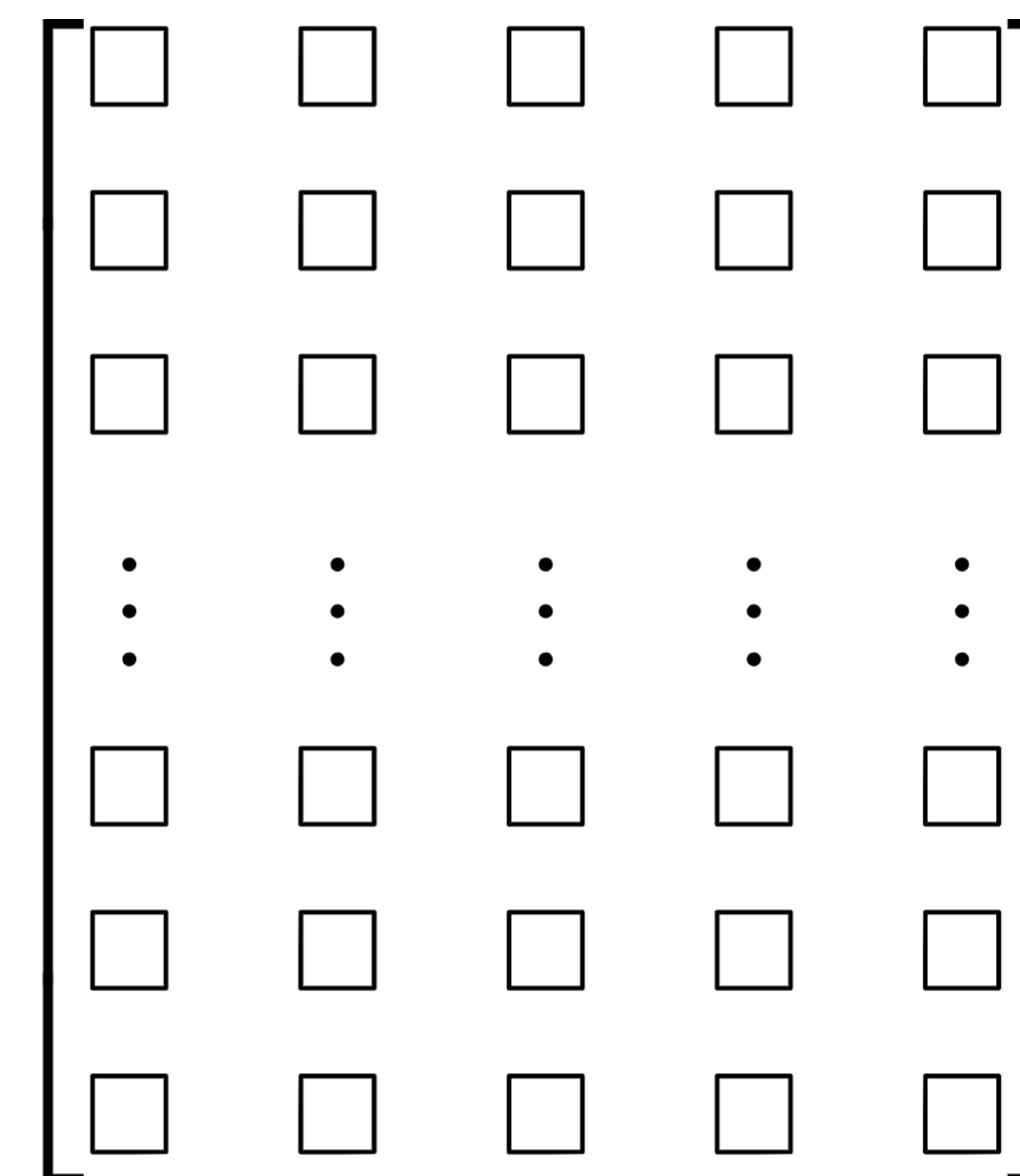
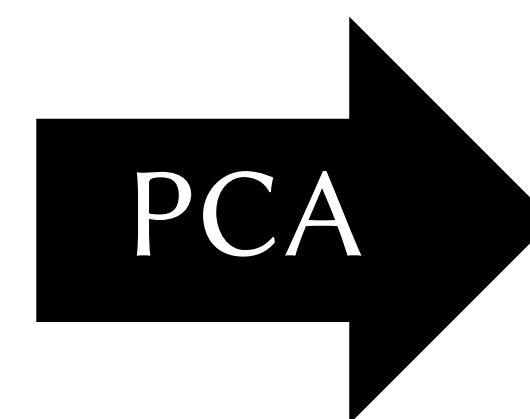


Backbone BRDF models

2) Linear PCA model [Mat03] [NJR15]



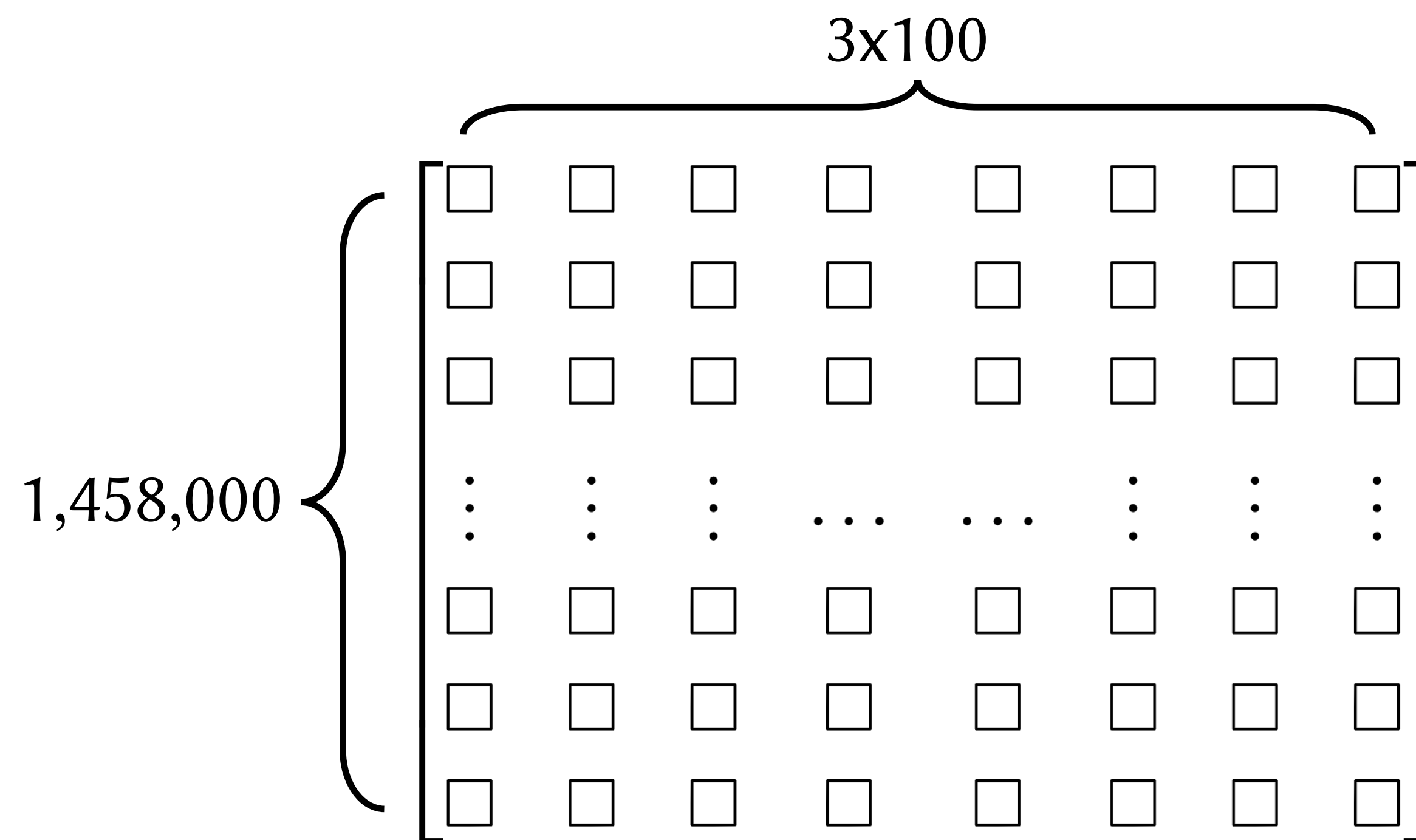
All 100 materials concatenated horizontally



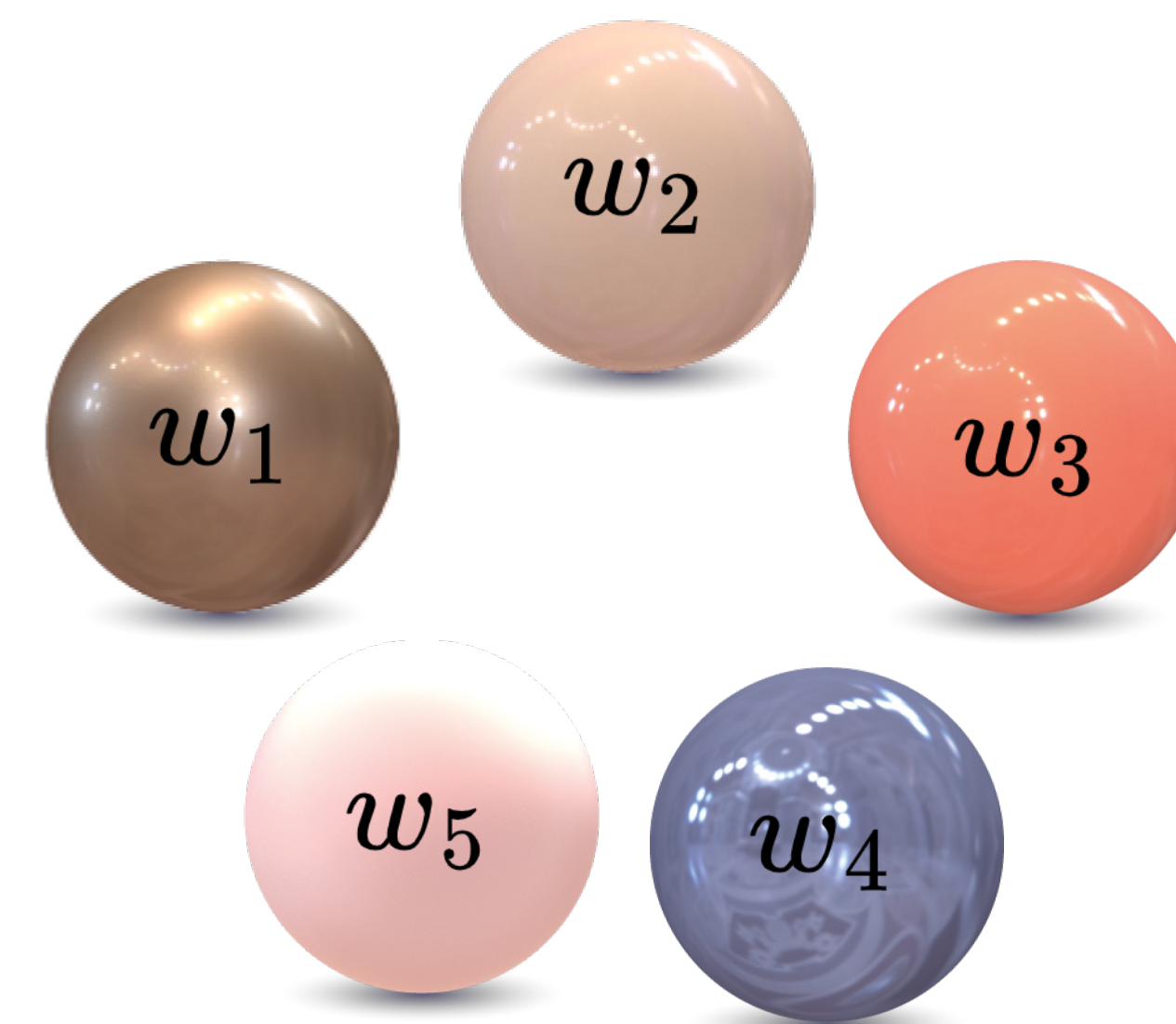
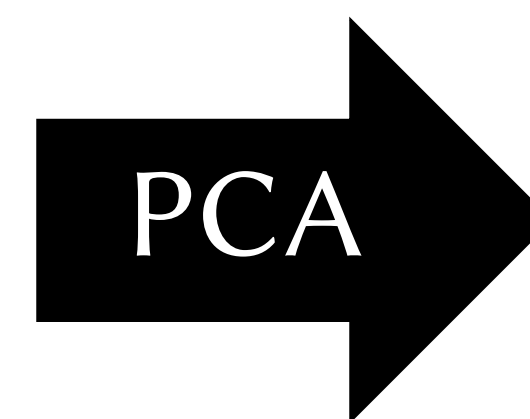
5 Principle Components

Backbone BRDF models

2) Linear PCA model [Mat03] [NJR15]



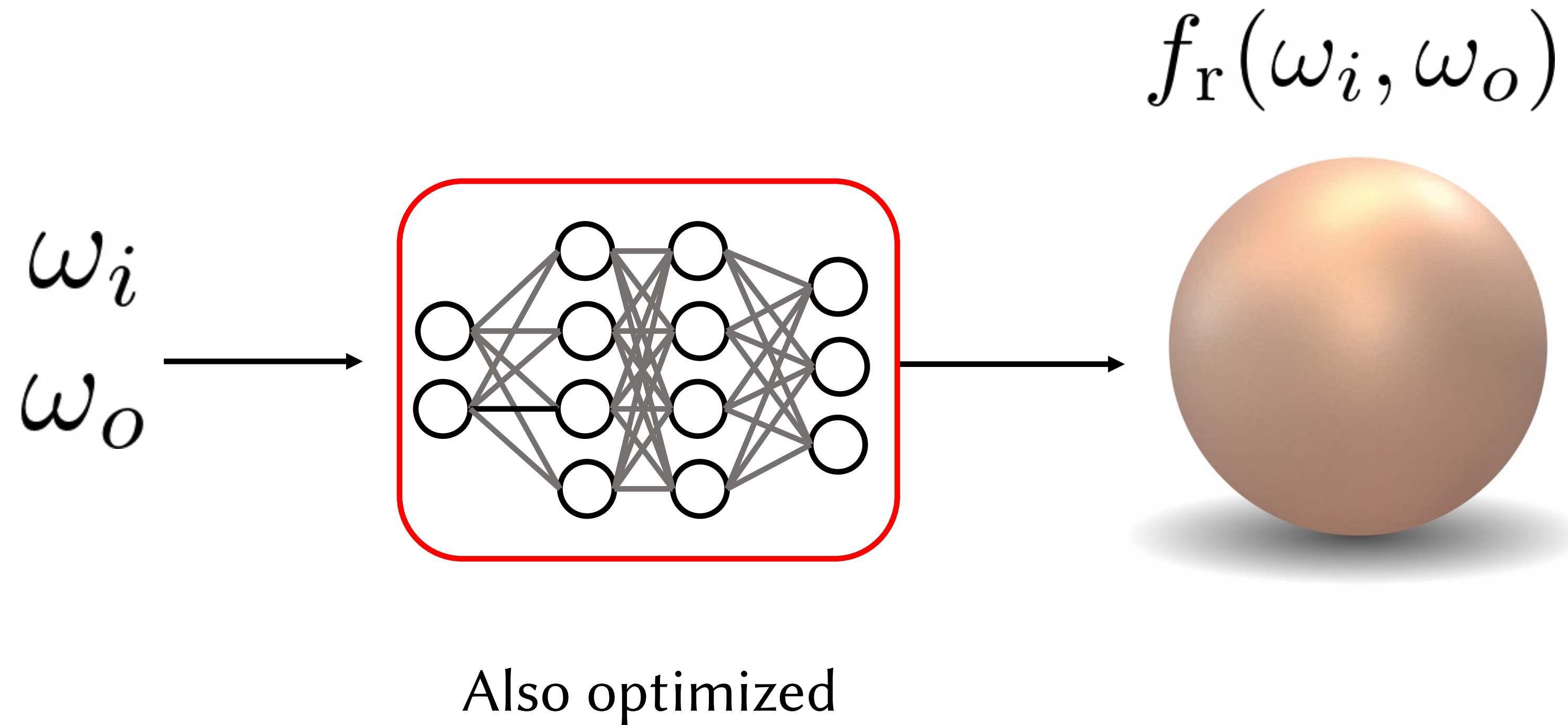
All 100 materials concatenated horizontally



fit weights by Least Squares

Backbone BRDF models

3) Neural BRDF [SRRW21]



Backbone BRDF models

- 1) Analytical [PB75] [CT82]
- 2) Linear PCA [Mat03] [NJR15]
- 3) Neural [SRRW21]

To optimize samples, our method **is orthogonal to ALL** these models

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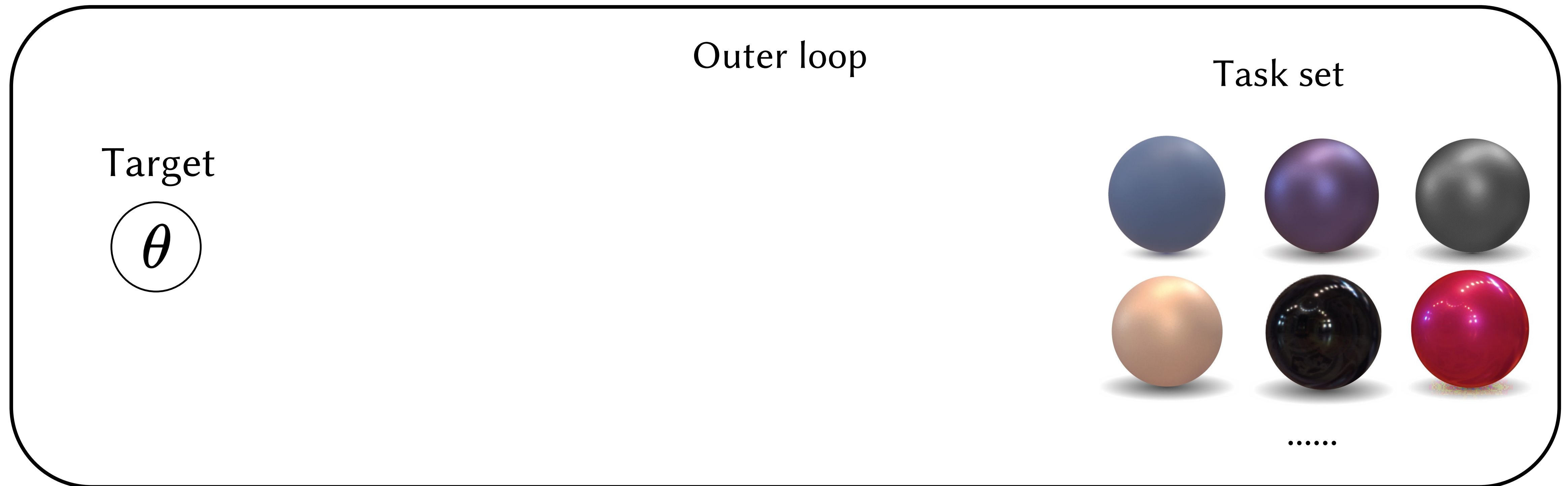
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Our solution

Our solution: meta-sampling

Meta learning: learning to learn

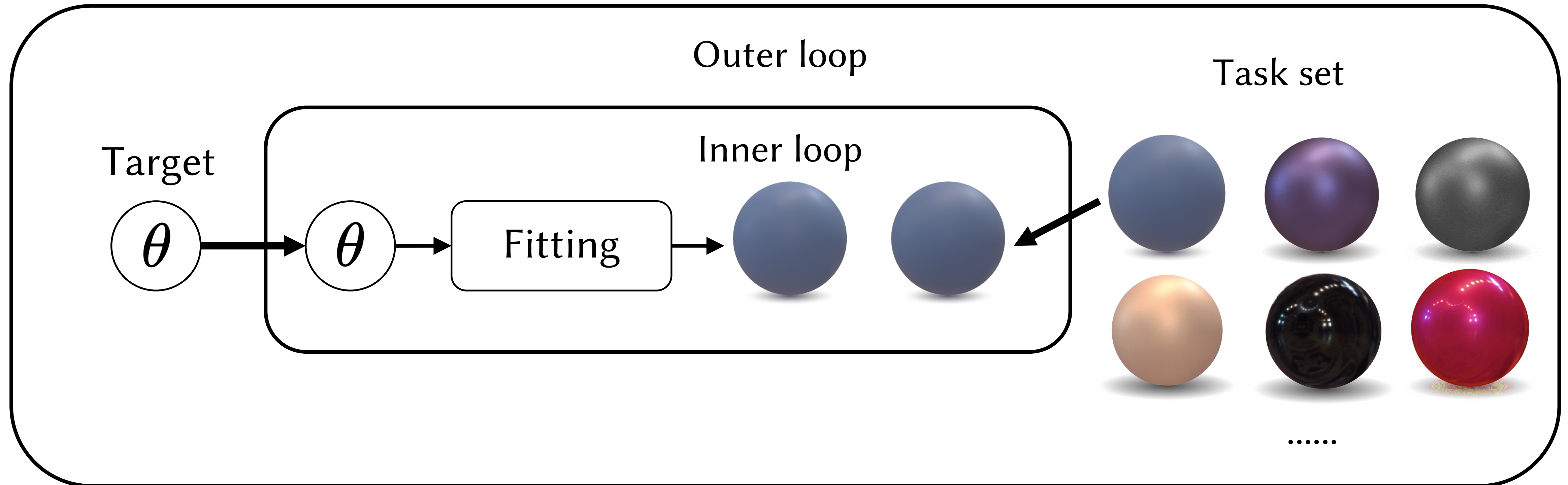
- Learn the commonalities (outer loop) from doing the same type of tasks (inner loop)



Our solution: meta-sampling

Meta learning: learning to learn

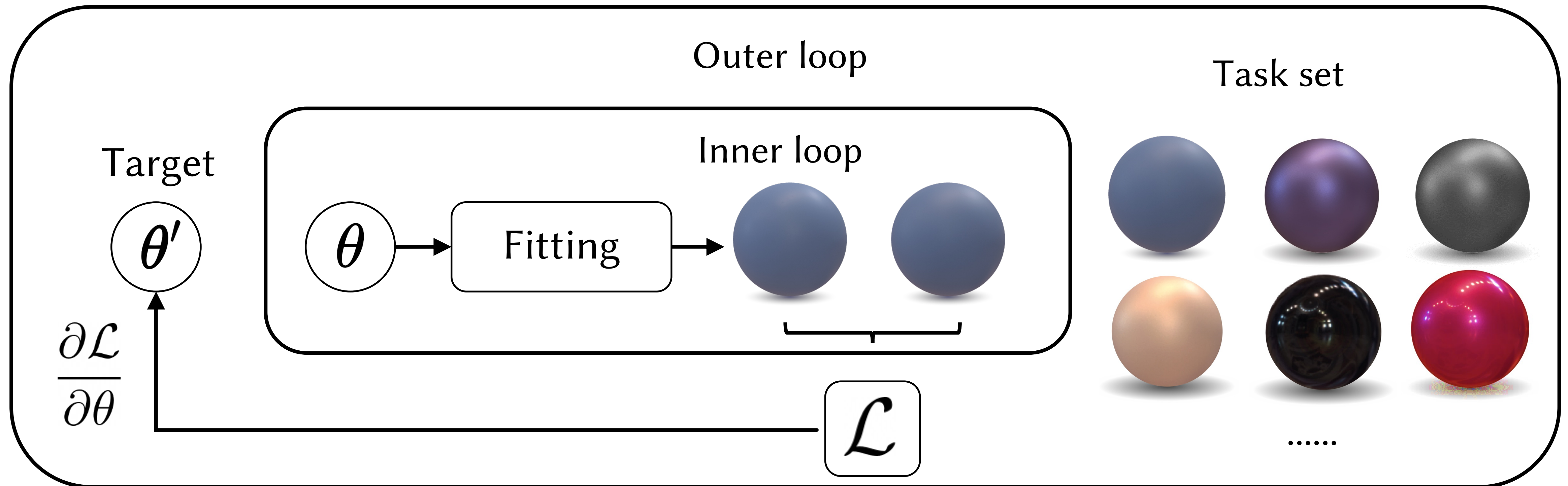
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Our solution: meta-sampling

Meta learning: learning to learn

- Learn the commonalities (outer loop) from doing the same type of tasks (inner loop)



Our solution: meta-sampling

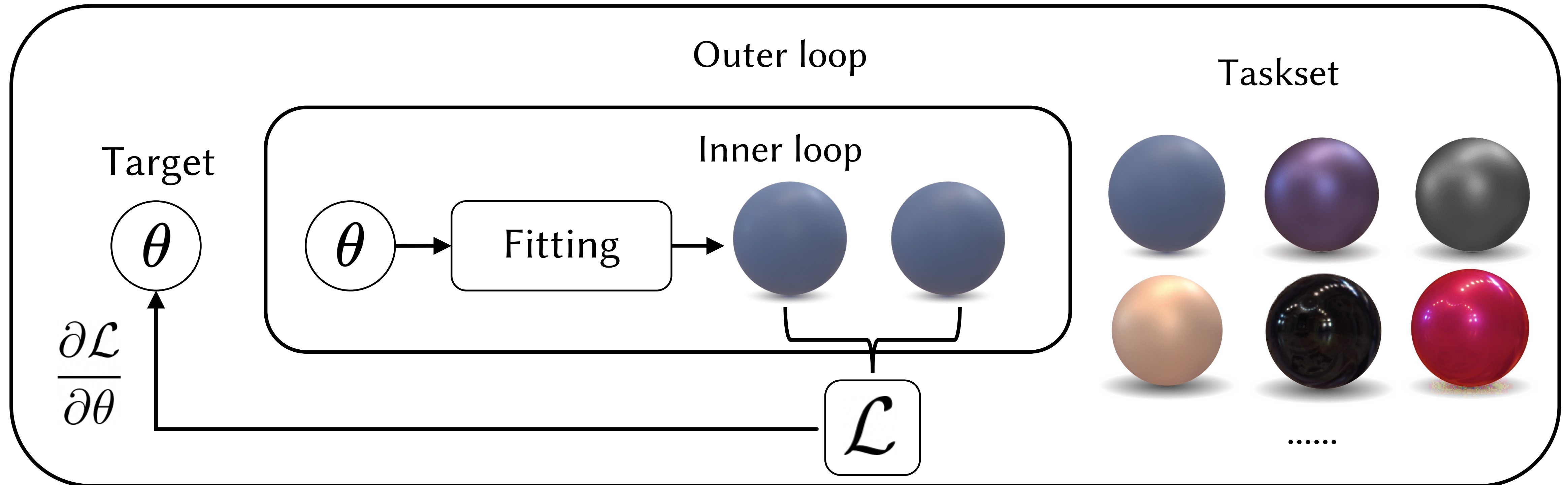
Meta learning in Computer Graphics

- Metappearance [FR22]
- MetaSDF [SCT*20]

Our solution: meta-sampling

Meta learning in Computer Graphics

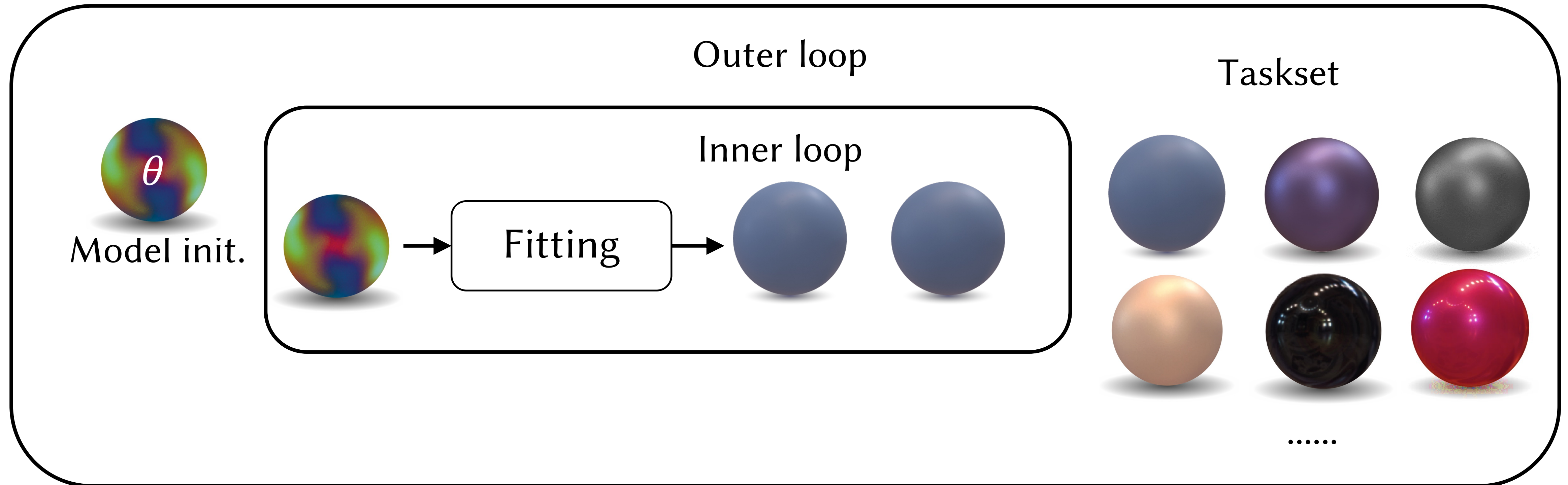
- Metappearance [FR22]
- MetaSDF [SCT*20]



Our solution: meta-sampling

Meta learning in Computer Graphics

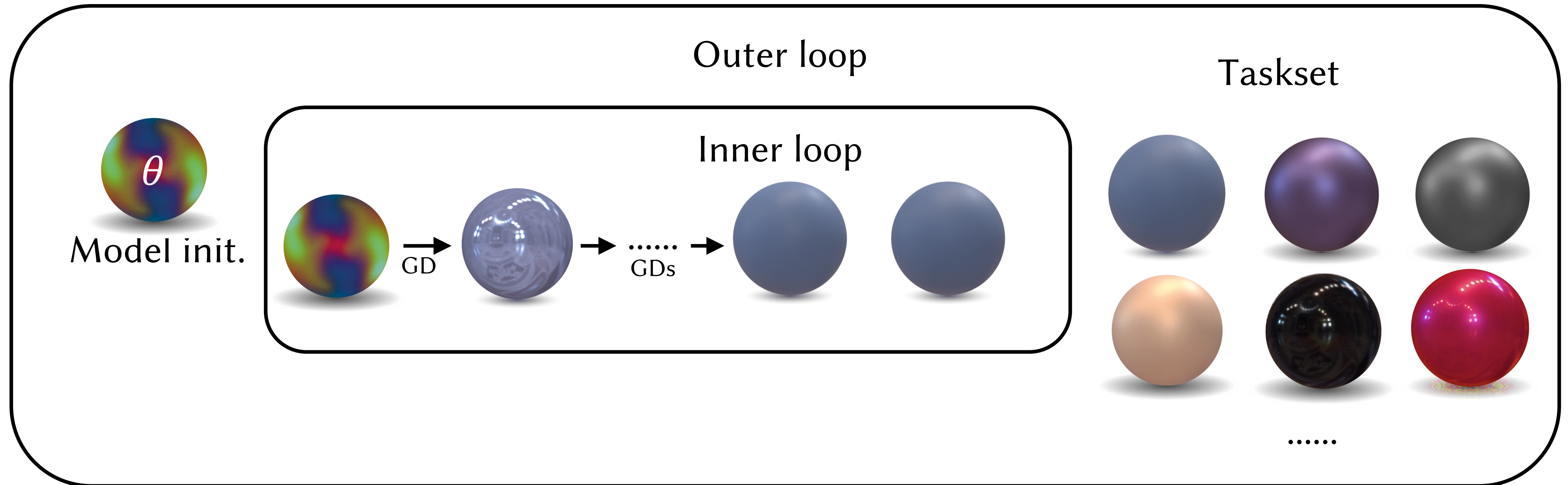
- Metappearance [FR22]
- MetaSDF [SCT*20]
- Target parameter: model init.



Our solution: meta-sampling

Meta learning in Computer Graphics

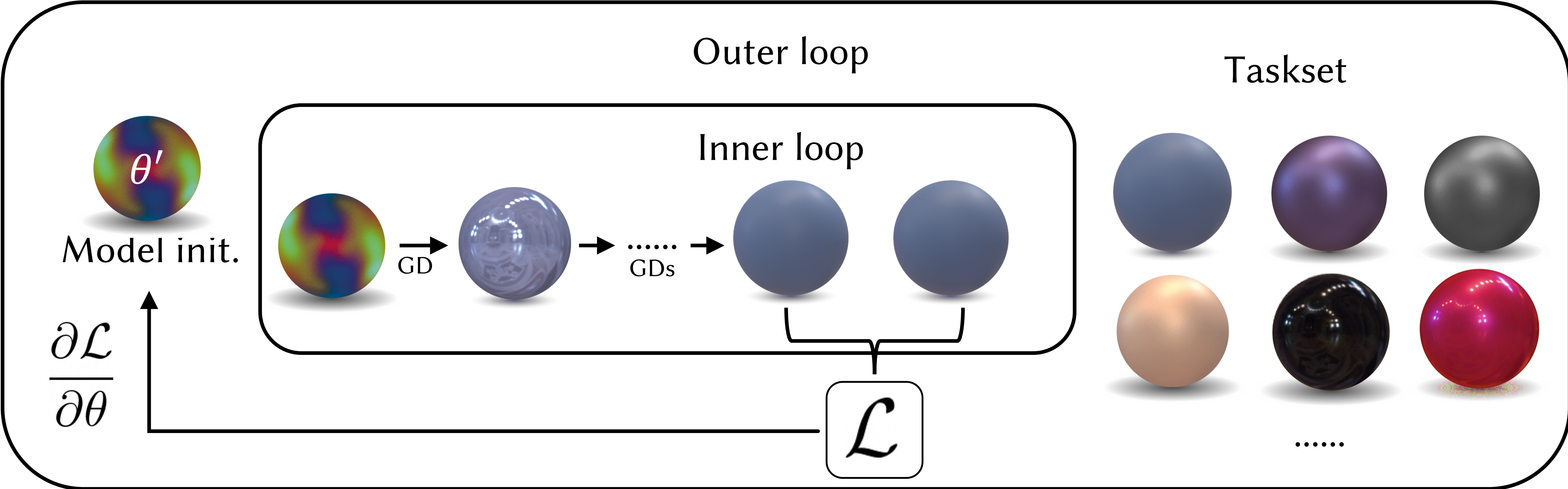
- Metappearance [FR22]
- MetaSDF [SCT*20]
- Target parameter: model init.
- Fitting: Stochastic Gradient Descent (SGD)



Our solution: meta-sampling

Meta learning in Computer Graphics

- Metappearance [FR22]
- MetaSDF [SCT*20]
- Target parameter: model init.
- Fitting: Stochastic Gradient Descent (SGD)



Our solution: meta-sampling

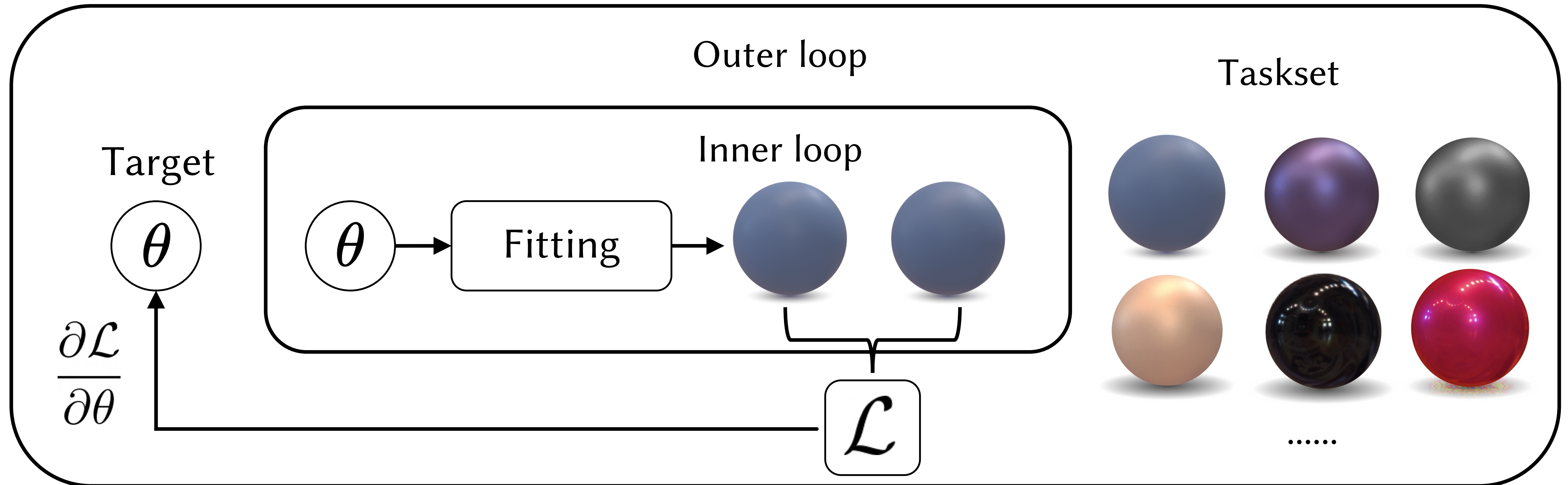
Meta sampling

- the sampler is our target parameter θ

Our solution: meta-sampling

Meta sampling

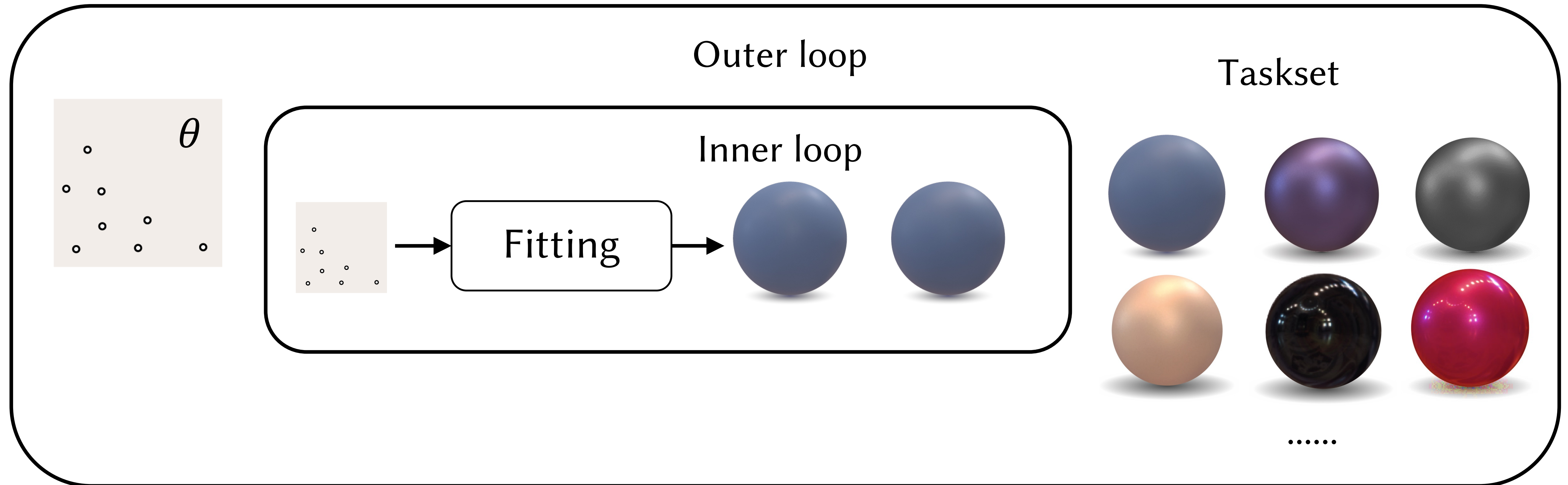
- the sampler is our target parameter θ



Our solution: meta-sampling

Meta sampling

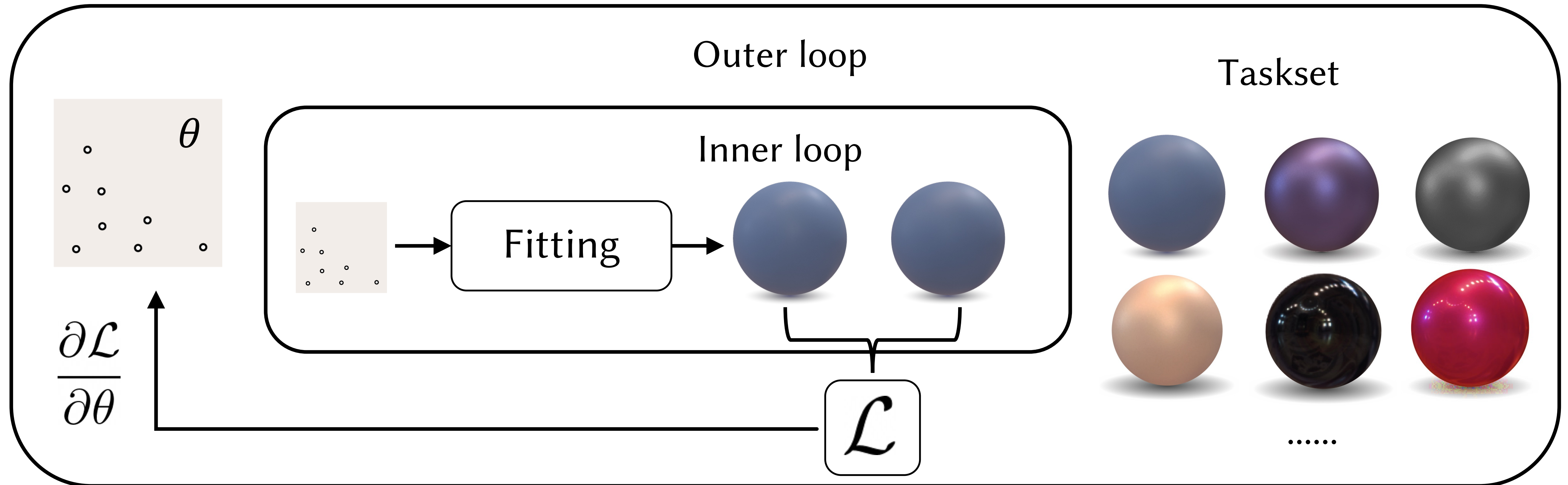
- the sampler is our target parameter θ



Our solution: meta-sampling

Meta sampling

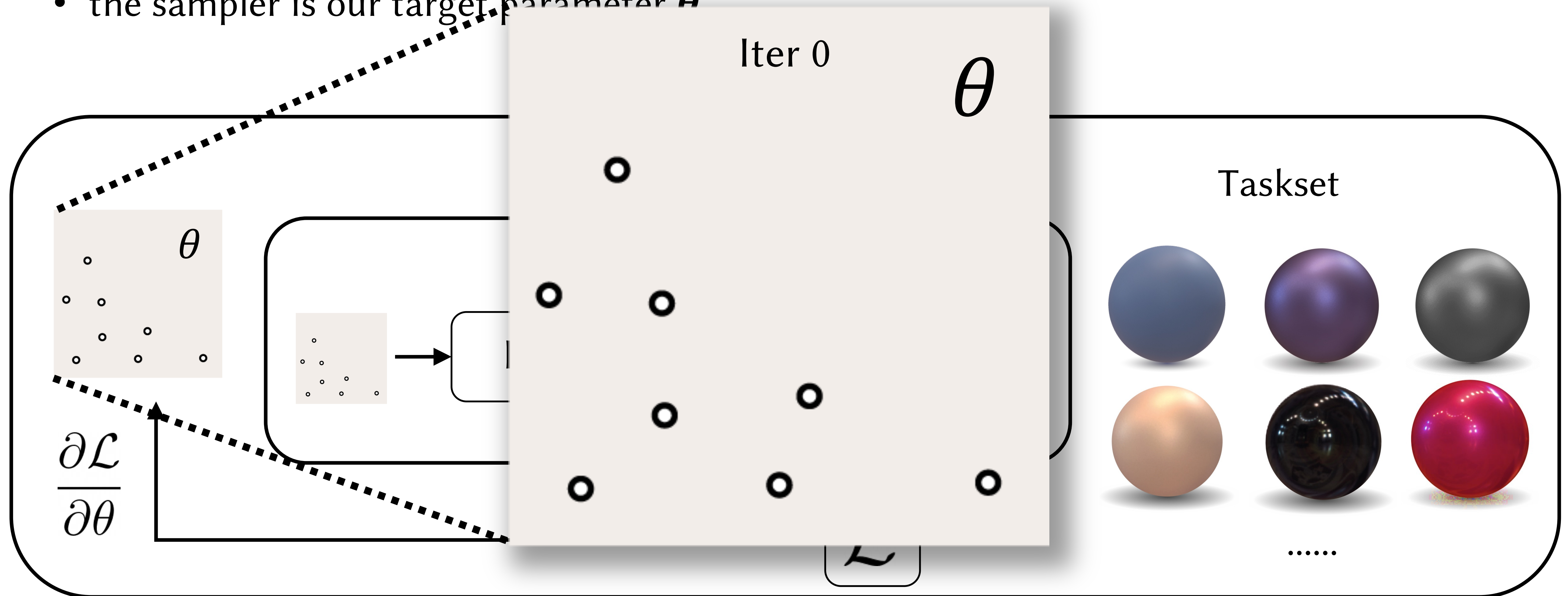
- the sampler is our target parameter θ



Our solution: meta-sampling

Meta sampling

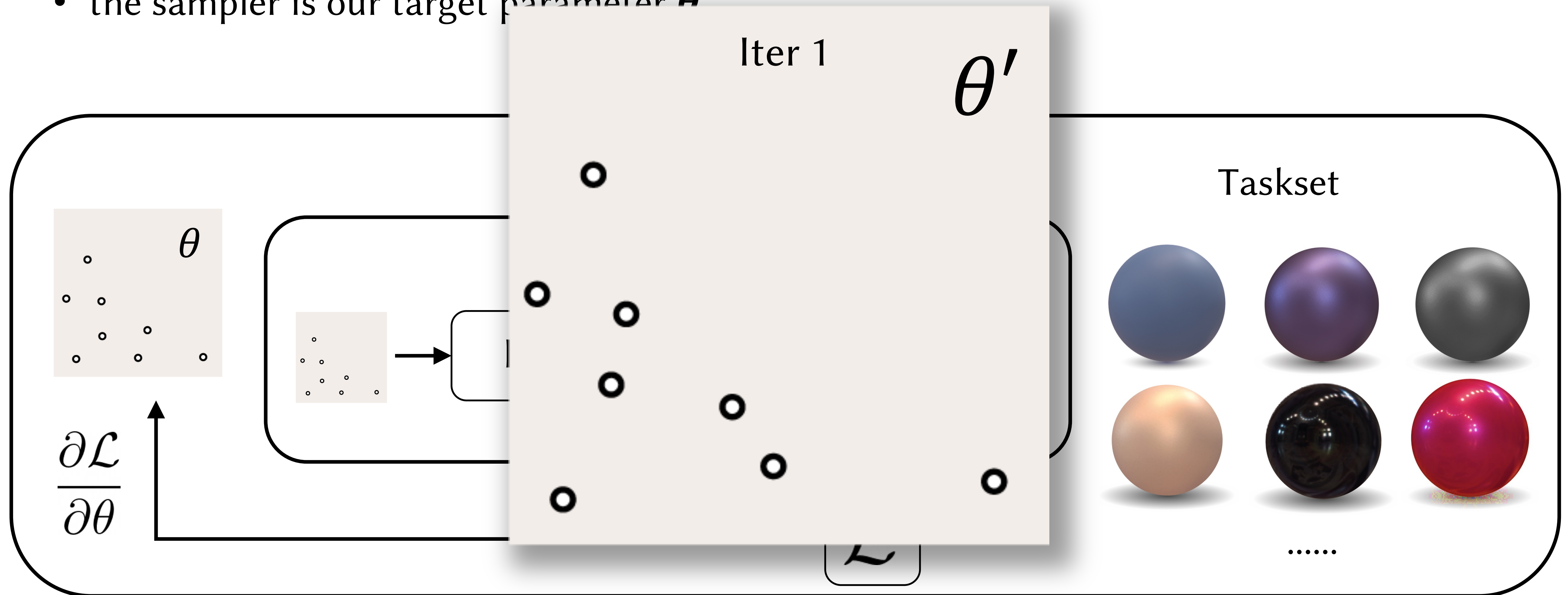
- the sampler is our target parameter θ



Our solution: meta-sampling

Meta sampling

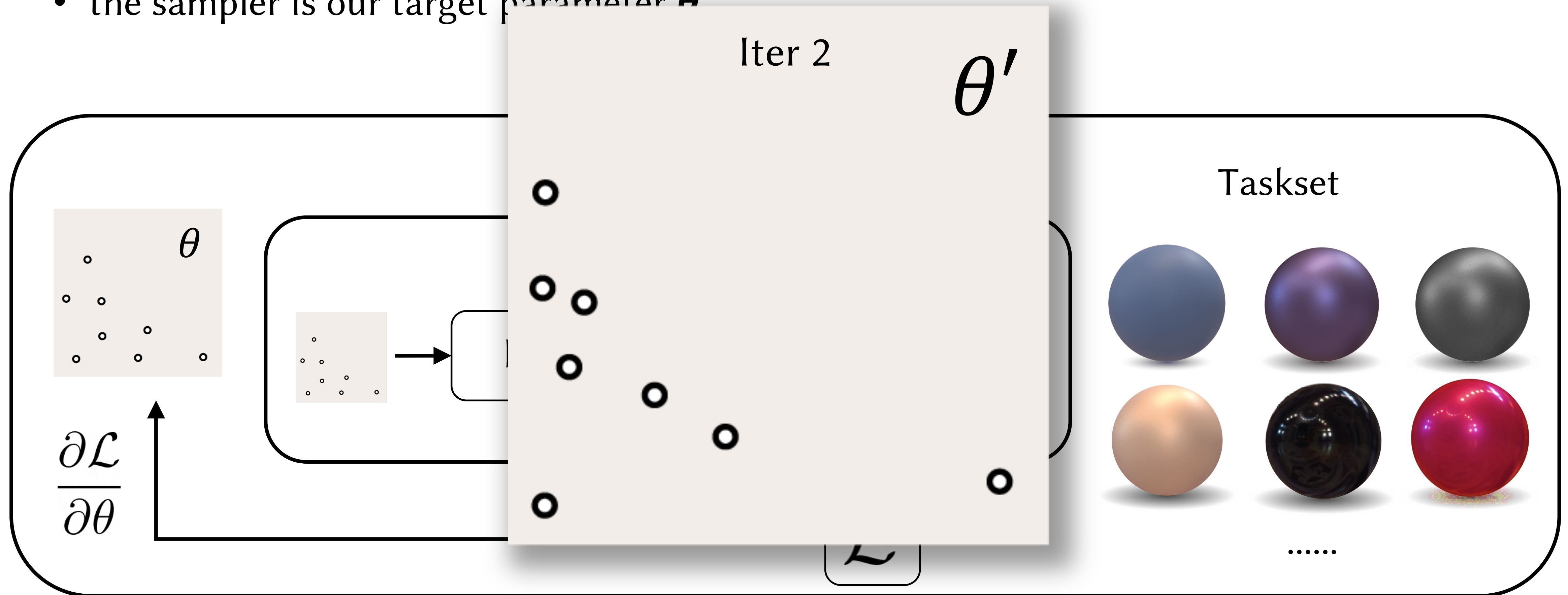
- the sampler is our target parameter θ



Our solution: meta-sampling

Meta sampling

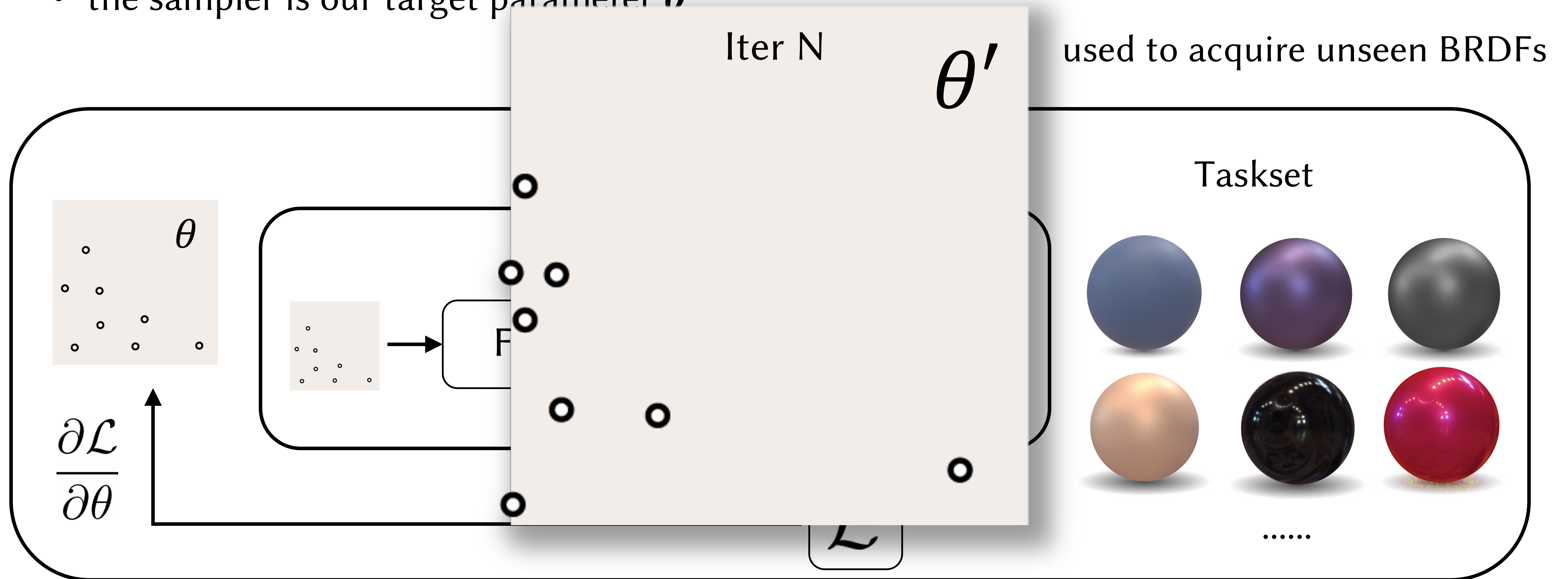
- the sampler is our target parameter θ



Our solution: meta-sampling

Meta sampling

- the sampler is our target parameter θ



For non-linear BRDF models

Using SGD in inner loop

- too many steps are prohibitive by cost
- 20 steps are not enough to fully make use of samples
- Use a meta-learned initialization [FR22]

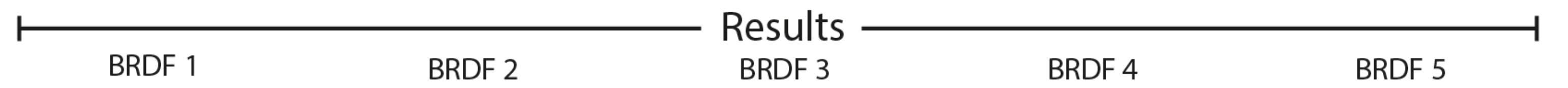
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Results

Optimization

Sampling



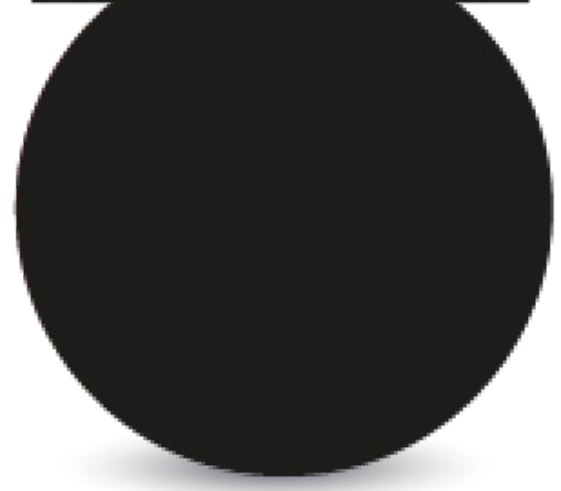
Reference



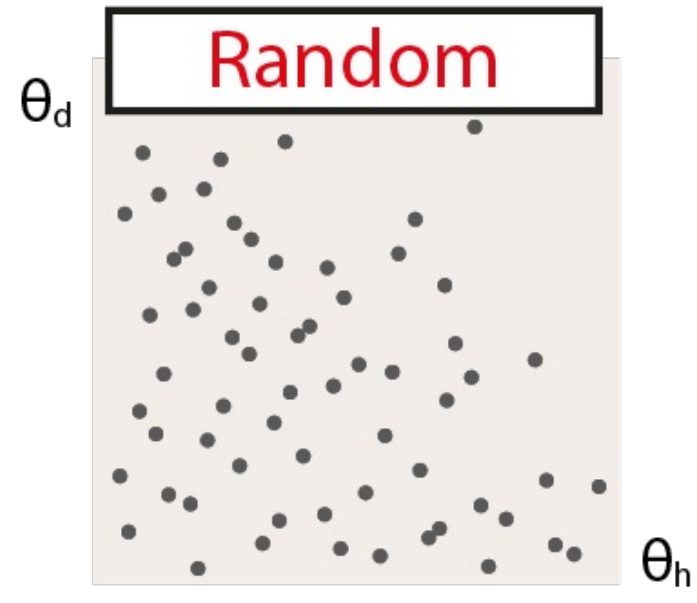
Random

Optimization

Random



Sampling



Results

BRDF 1



BRDF 2



BRDF 3



BRDF 4

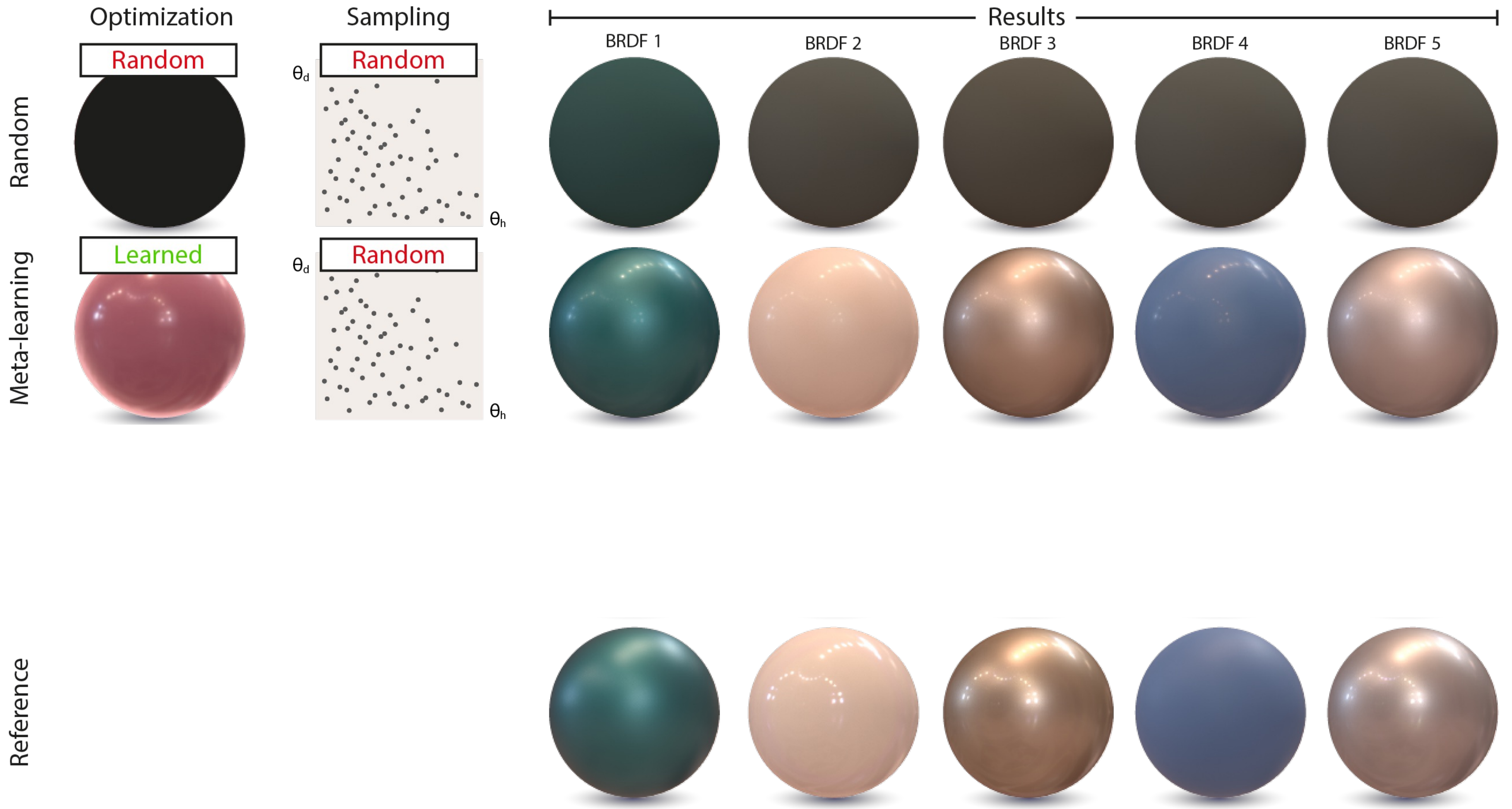


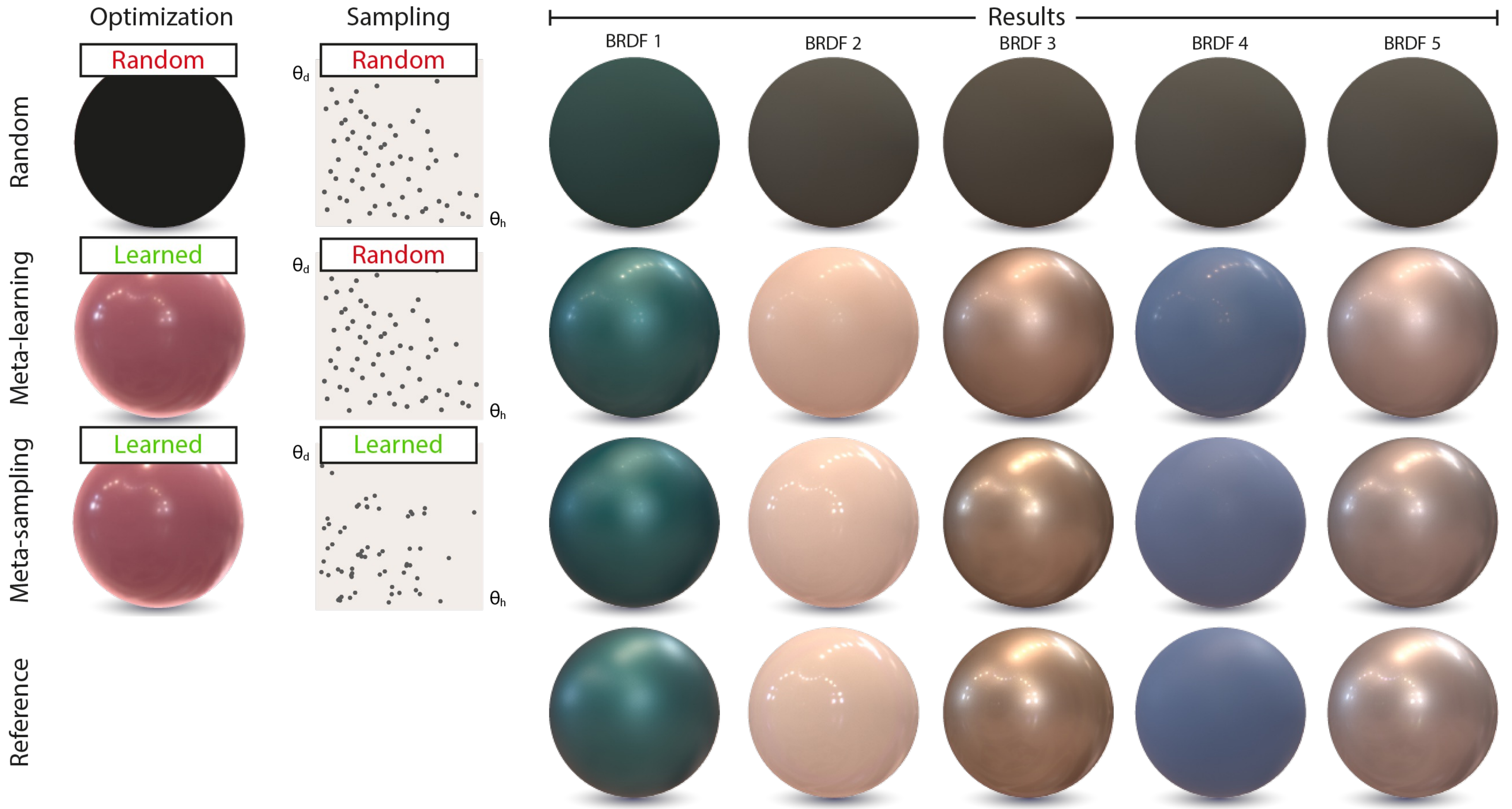
BRDF 5



Reference







#samples = 8,
for the diffuse BRDF

Random

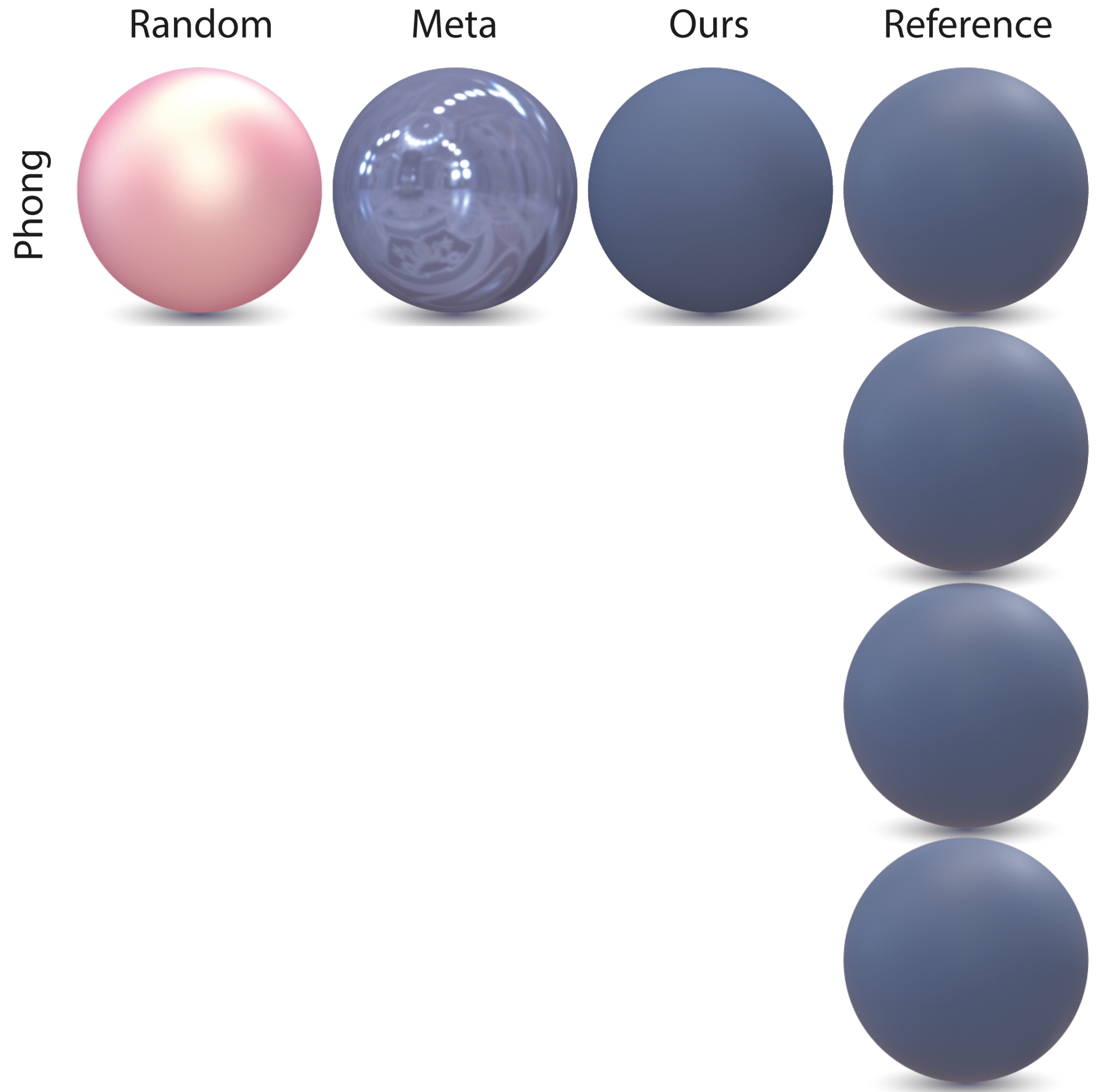
Meta

Ours

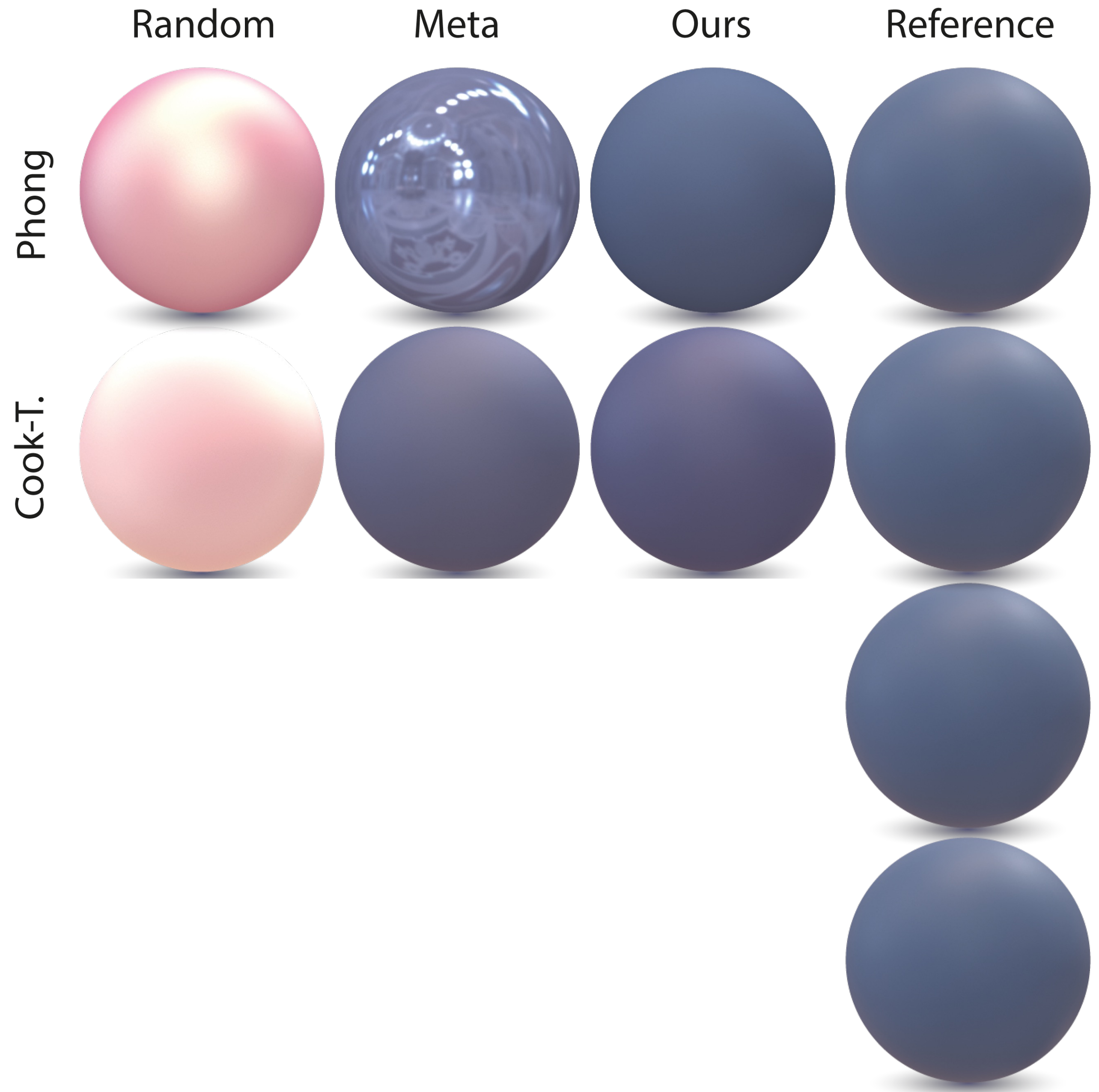
Reference



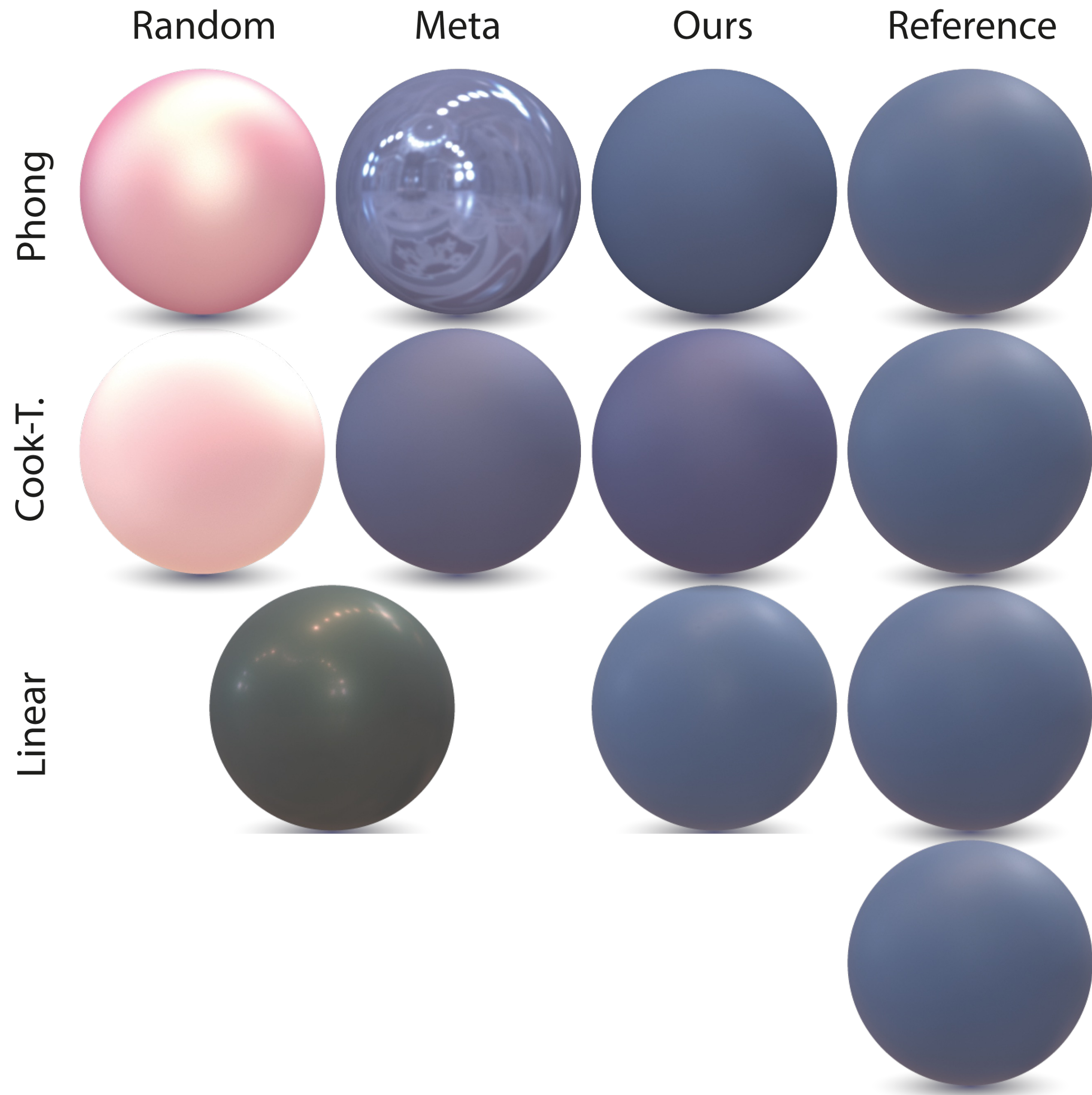
#samples = 8,
for the diffuse BRDF



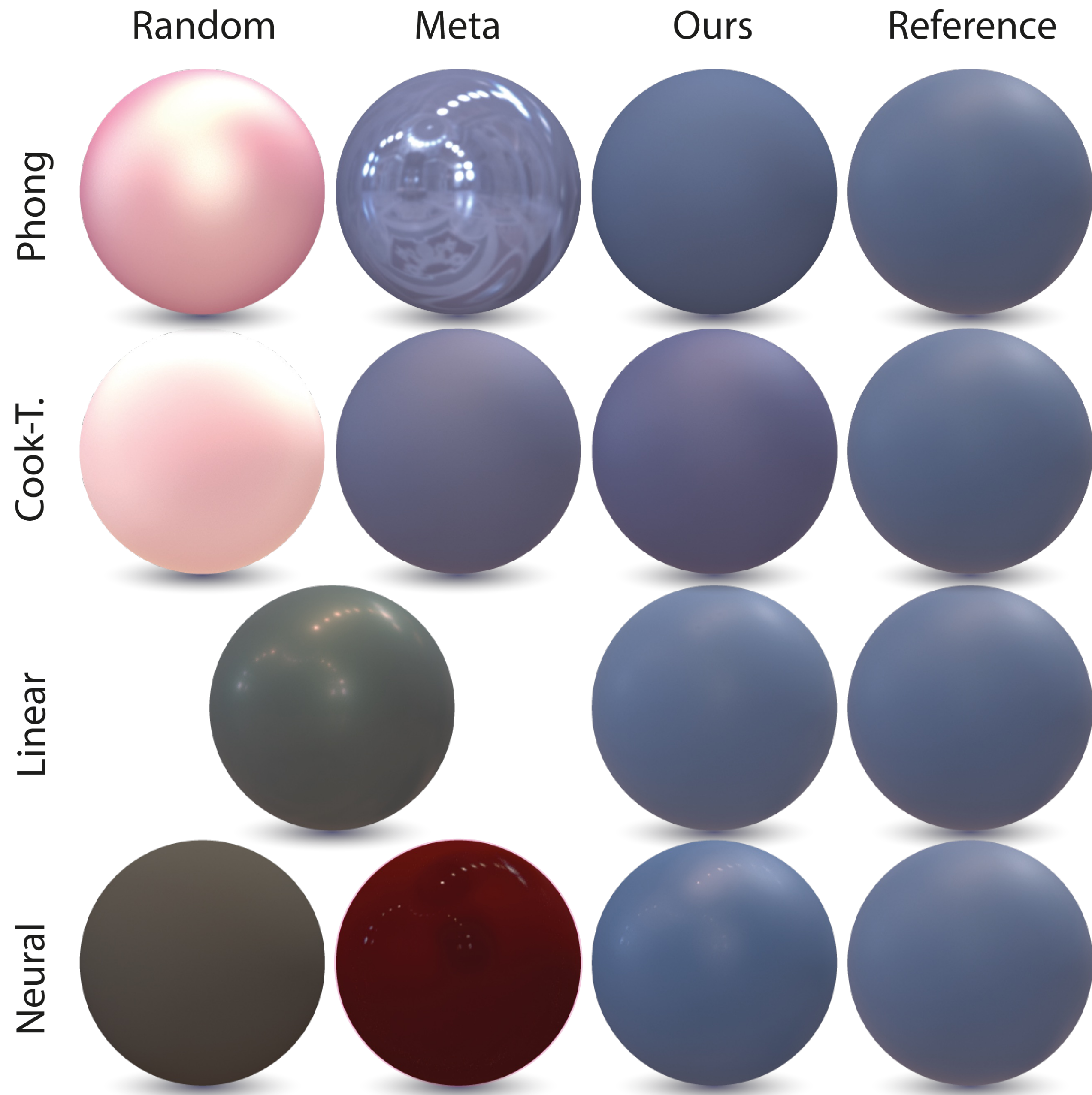
#samples = 8,
for the diffuse BRDF



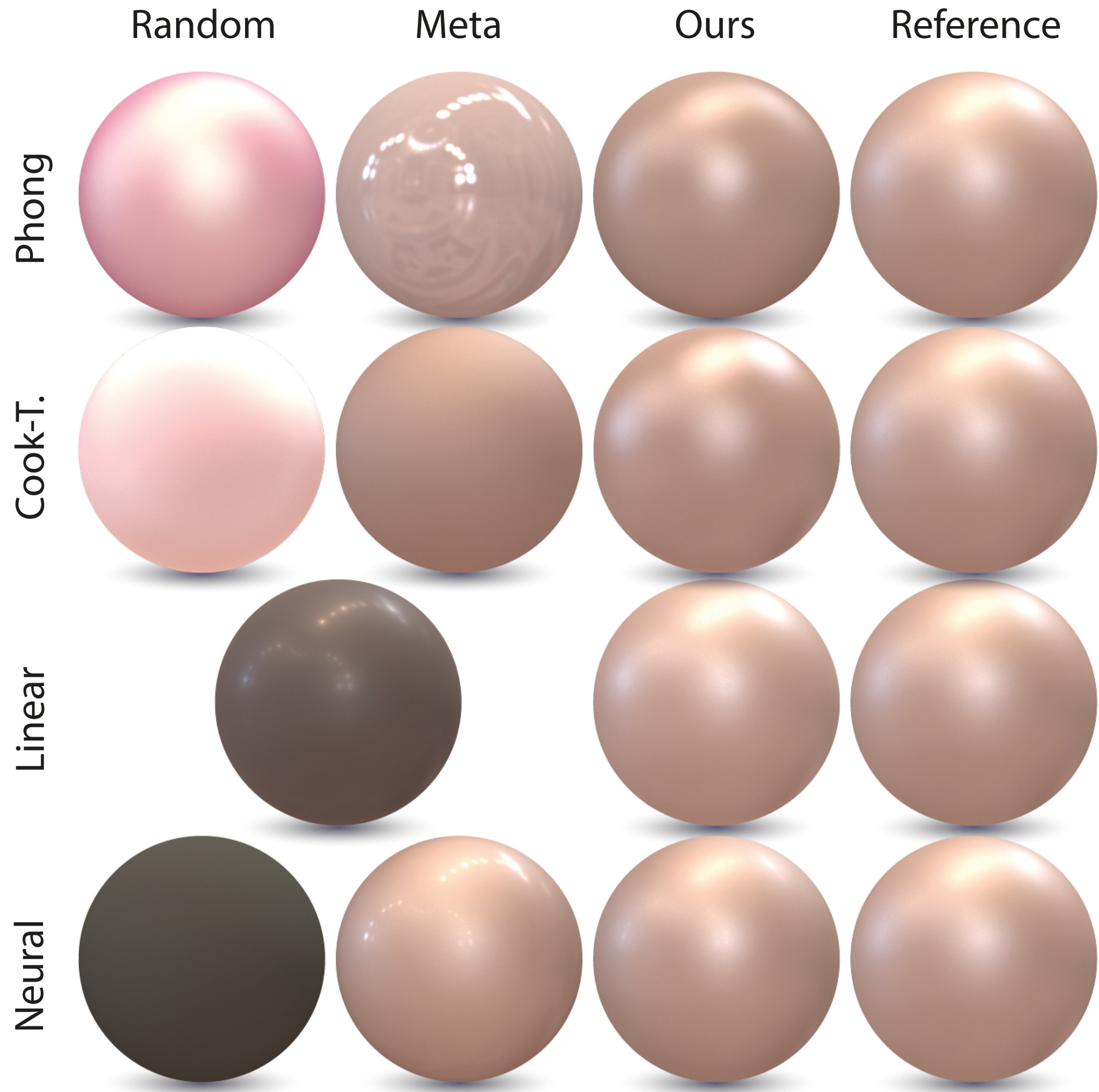
#samples = 8,
for the diffuse BRDF



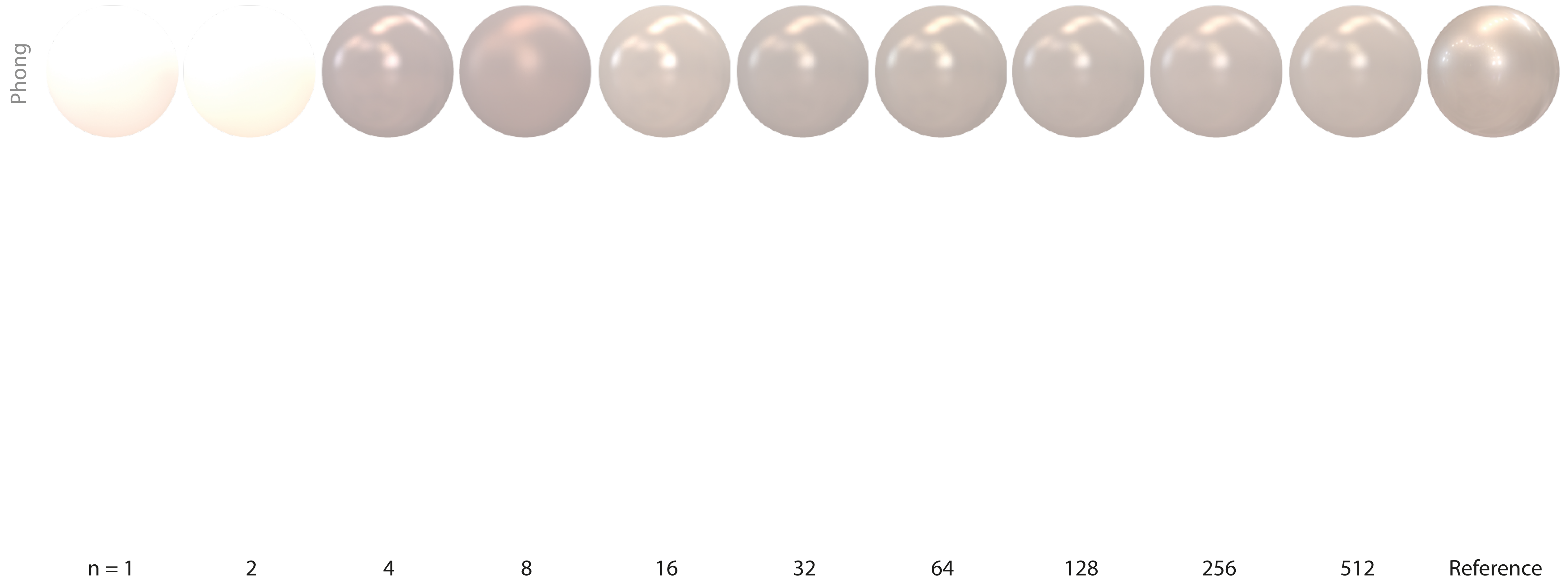
#samples = 8,
for the diffuse BRDF



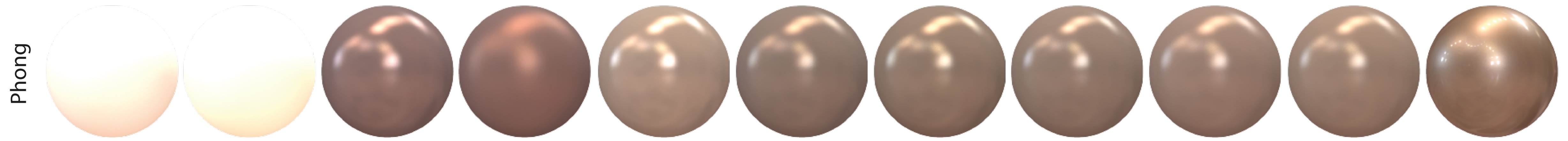
#samples = 32,
for the glossy BRDF



Increasing #samples



Increasing #samples



n = 1

2

4

8

16

32

64

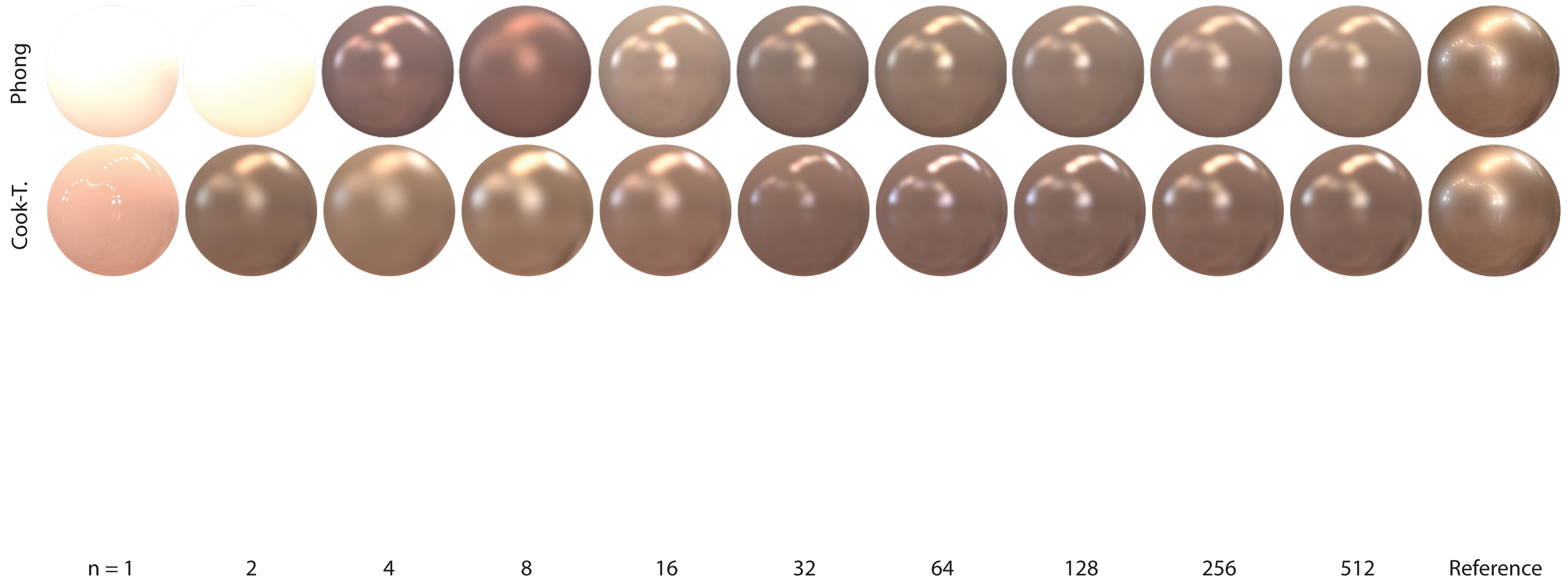
128

256

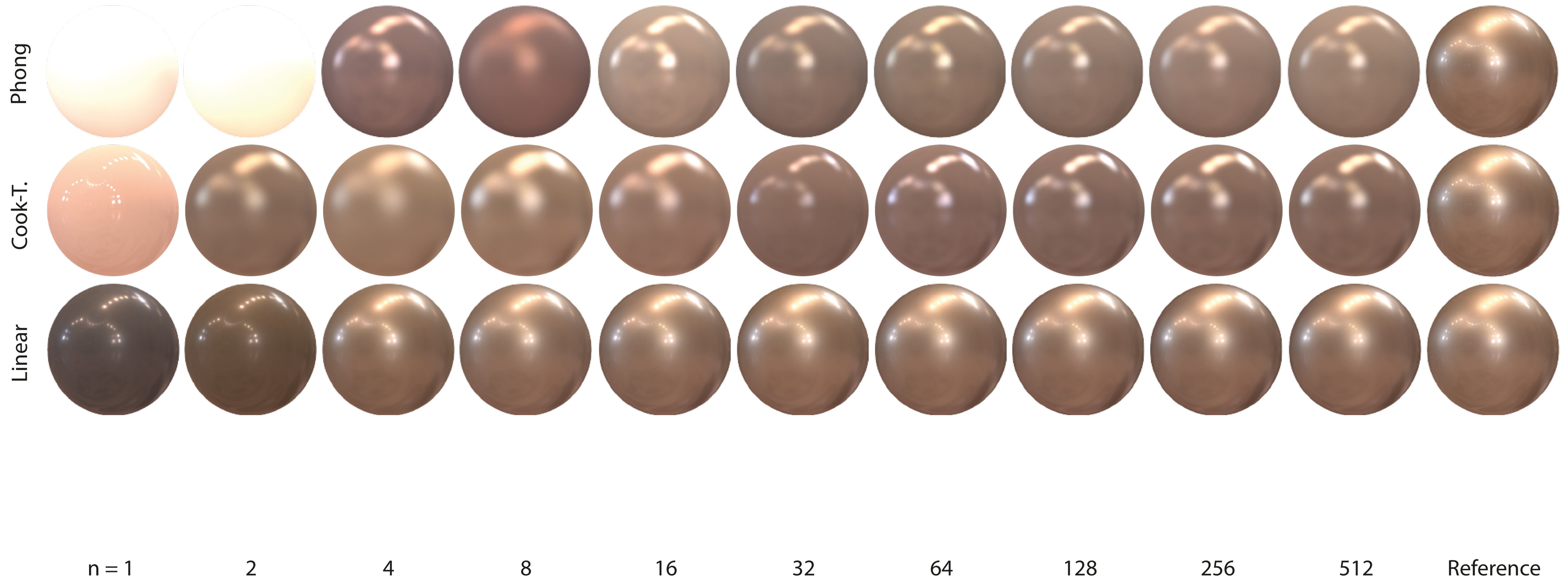
512

Reference

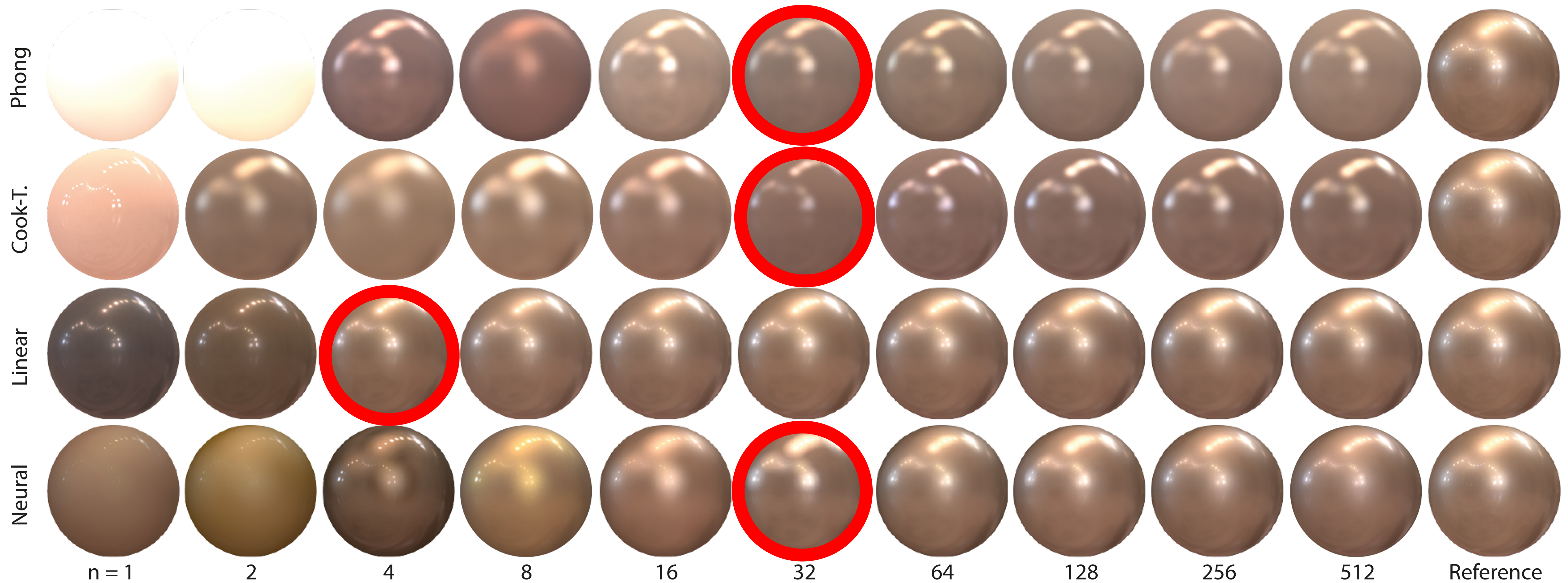
Increasing #samples



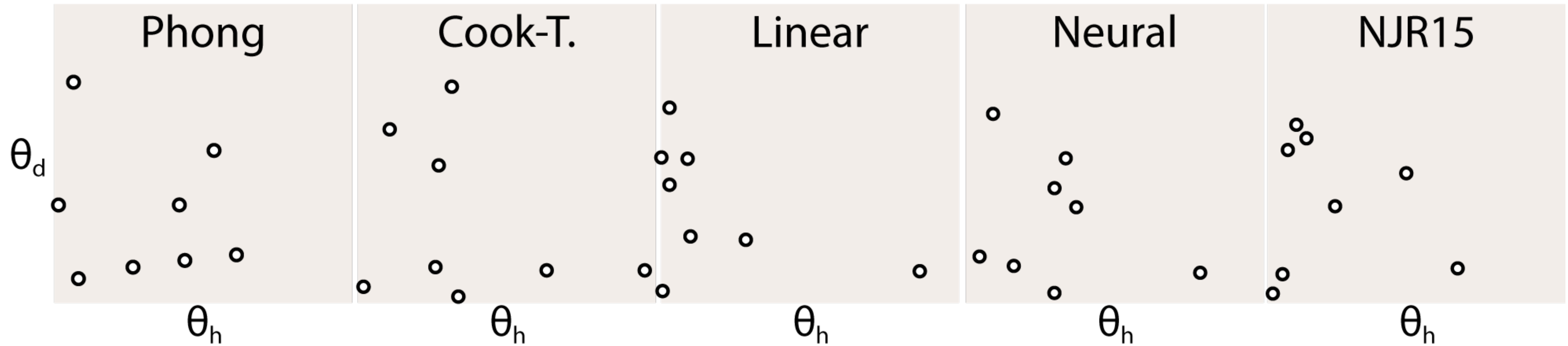
Increasing #samples



Increasing #samples



Learned patterns



Still difficult to interpret these patterns

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Summary

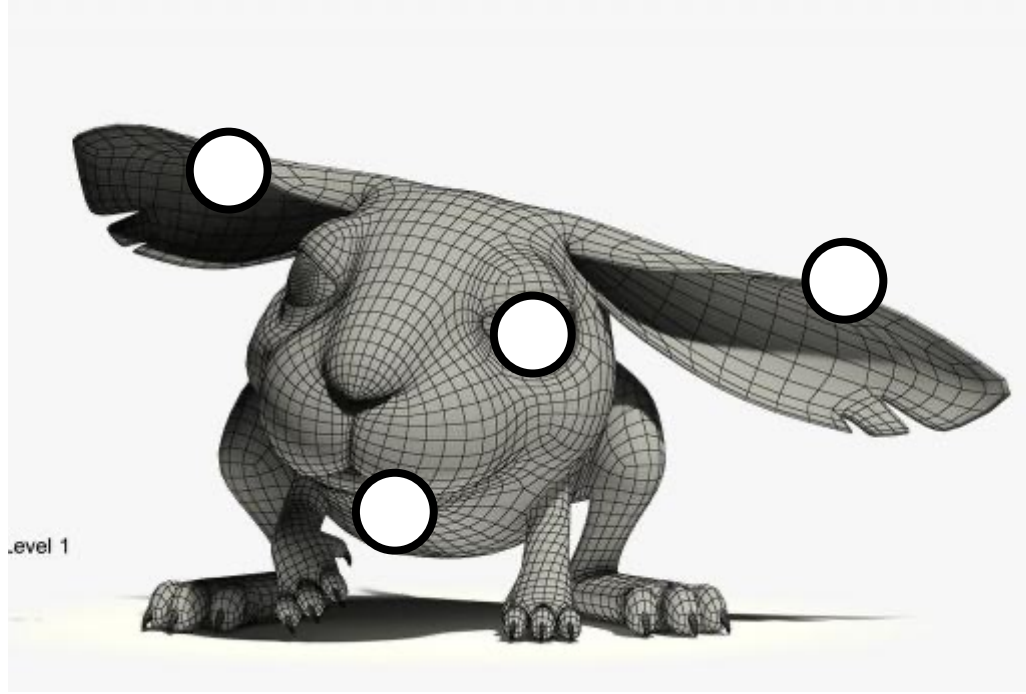
Meta sampling

- Model-agnostic: Neural, Linear, and Analytical... all good!
- Performance
 - Reconstruct high-quality BRDFs by only 4~32 samples
 - 5 orders of magnitudes fewer
- Compared to [NJR15]
 - Extended to more BRDF models
 - Better loss using same number of samples

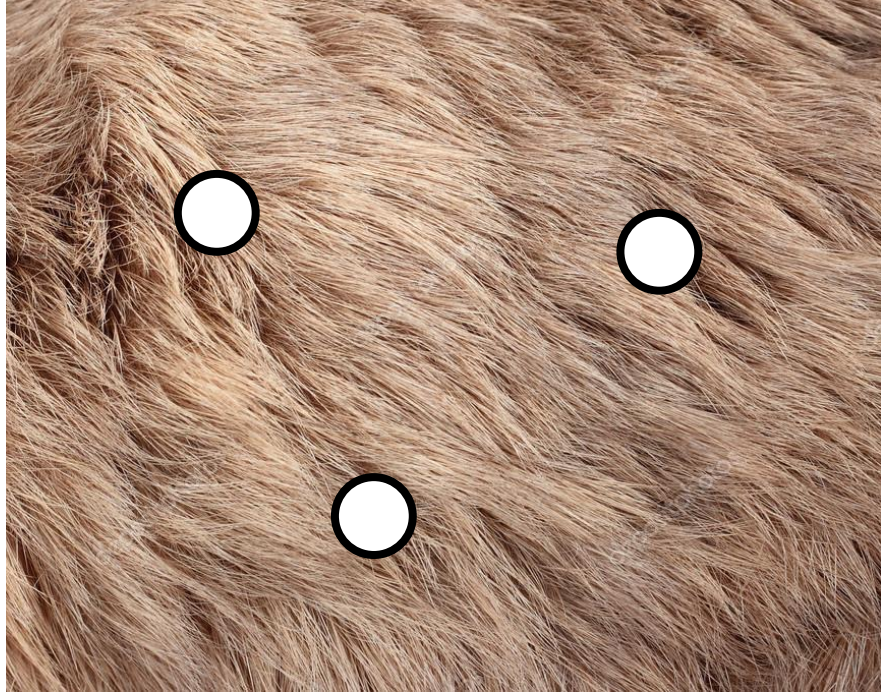
Future work



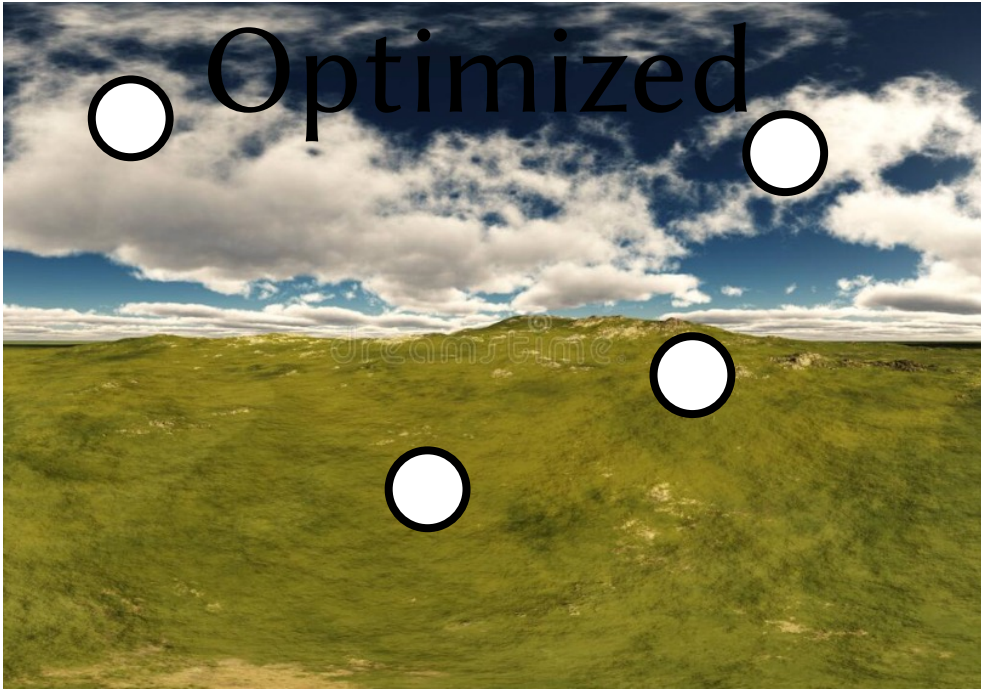
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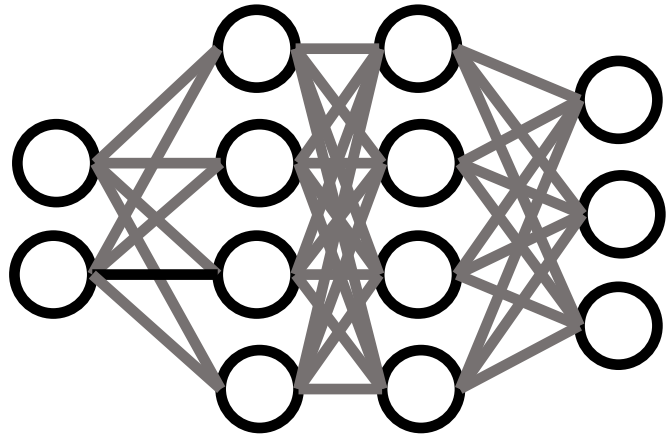
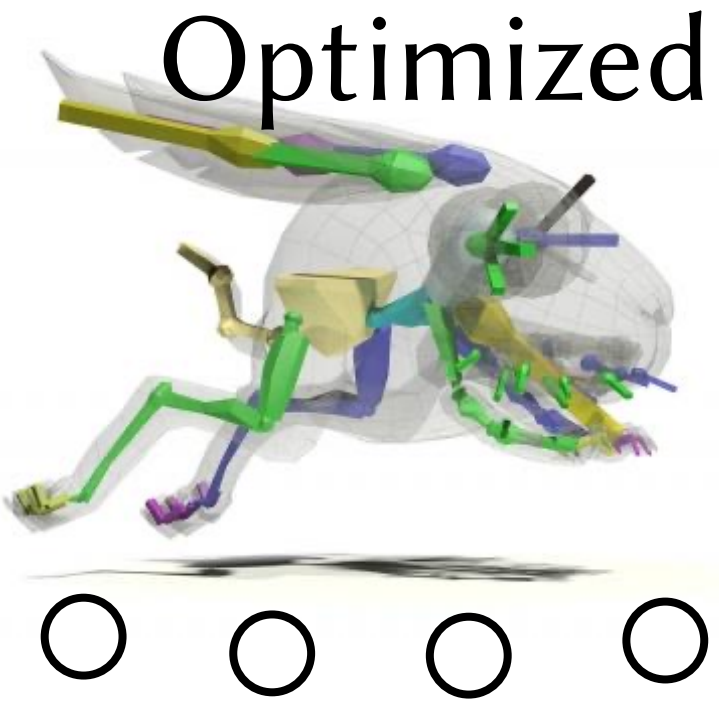
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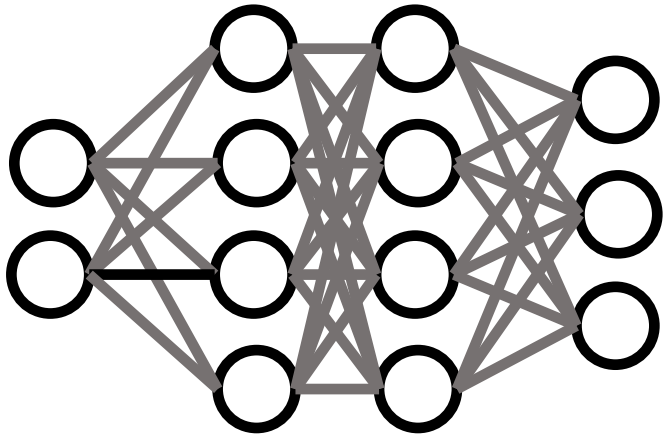
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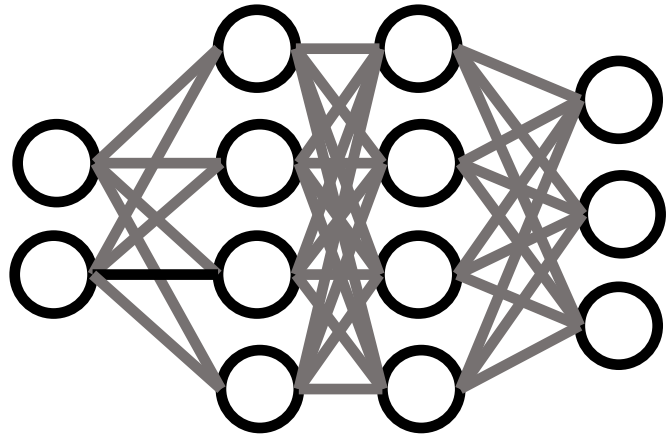
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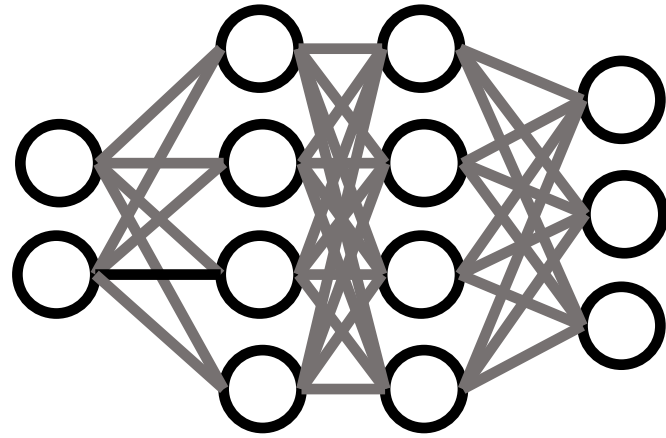
Tomorrow?



Today



Tomorrow?

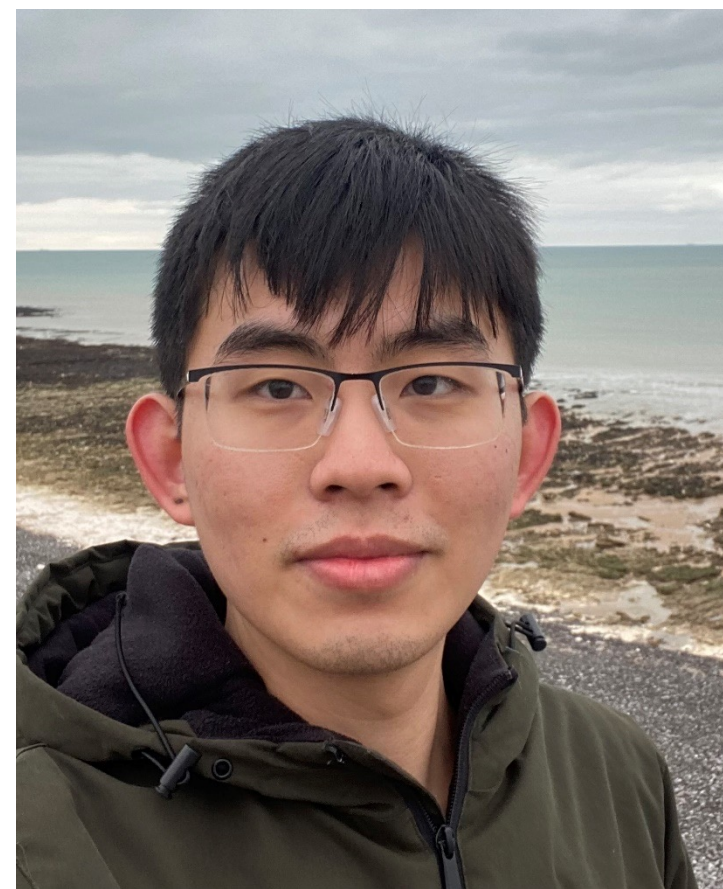


Tomorrow?

Meta-sampling: Learning to Learn and Sample BRDFs



ryushinn.github.io/metasampling



Chen
Liu



Michael
Fischer



Tobias
Ritschel

We acknowledged funding by Meta Reality Labs



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Thank you!